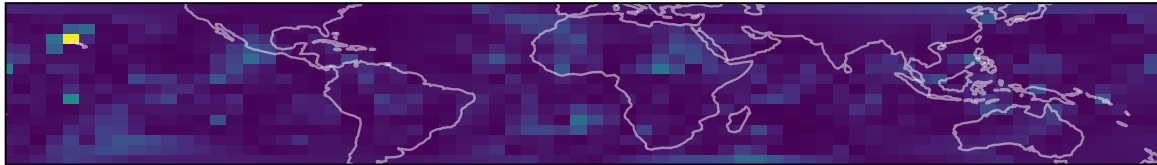


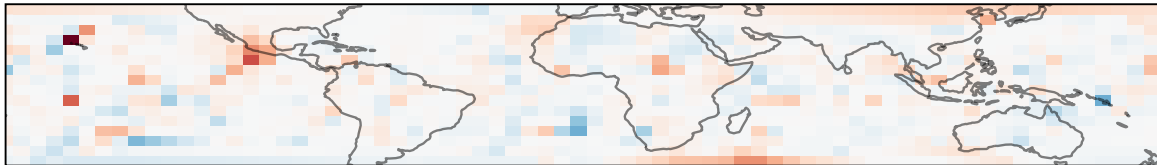
Previously, on Strateole-2...

- Better estimation of k , l , v
- *Net* Momentum Flux from COSMIC2

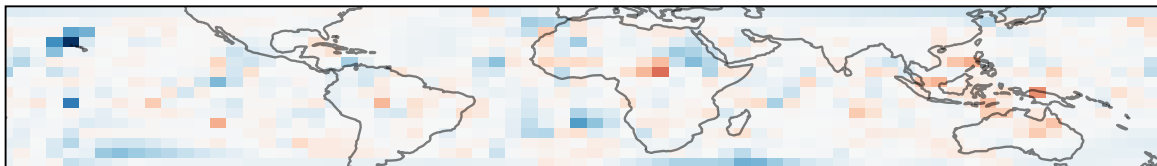
(a) Absolute Momentum Flux @ 26 km, 31 Dec 2020



(c) Eastward Momentum Flux @ 26 km, 31 Dec 2020



(e) Northward Momentum Flux @ 26 km, 31 Dec 2020

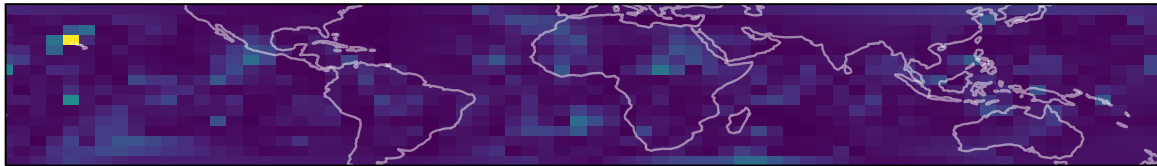


Previously, on Strateole-2...

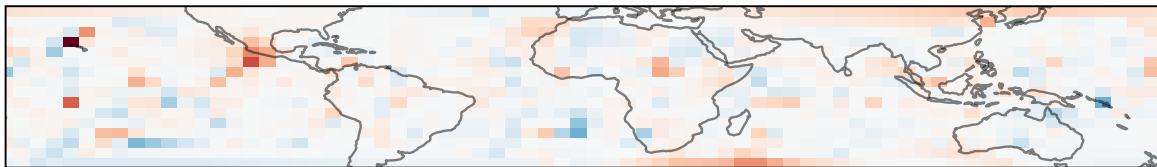
- Better estimation of k , l , v
- **Not** Momentum Flux from COSMIC2

Special thanks to
Hamid Pahlavan

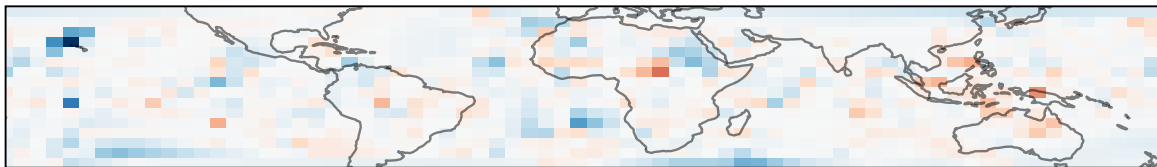
(a) Absolute Momentum Flux @ 26 km, 31 Dec 2020



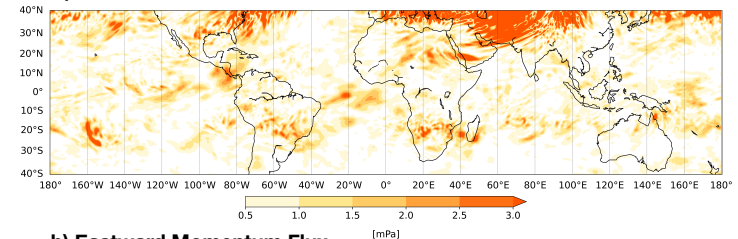
(c) Eastward Momentum Flux @ 26 km, 31 Dec 2020



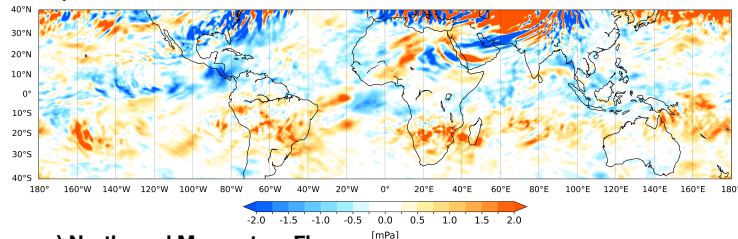
(e) Northward Momentum Flux @ 26 km, 31 Dec 2020



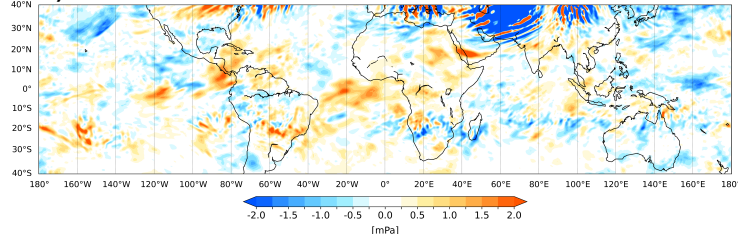
a) Absolute Momentum Flux



b) Eastward Momentum Flux



c) Northward Momentum Flux



Today

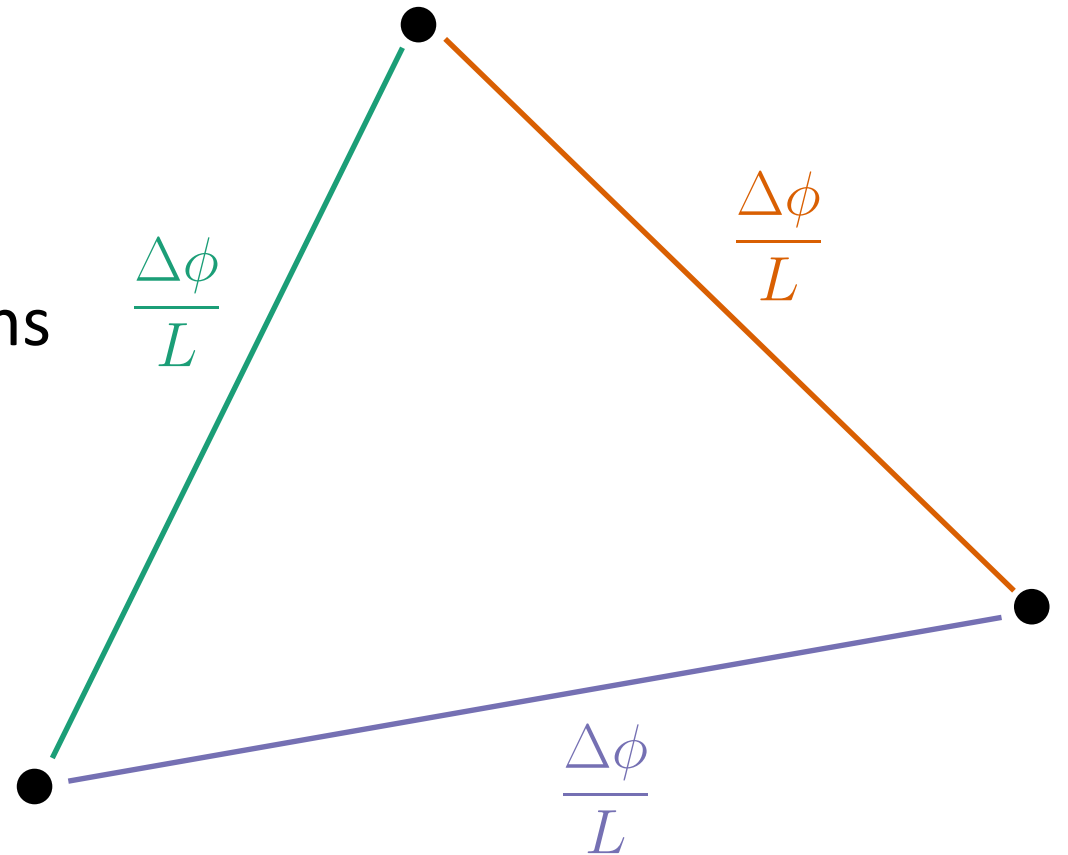
- Review
 - The challenge with GPS RO
 - The usual approach
- Document
 - My new approach
 - Where I'm stuck
- Ideas where to go next

GPS RO is great at A , m , bad at k , l , v

- 2 profiles: easy
- 3 profiles: hard
- 4 profiles: impossible*

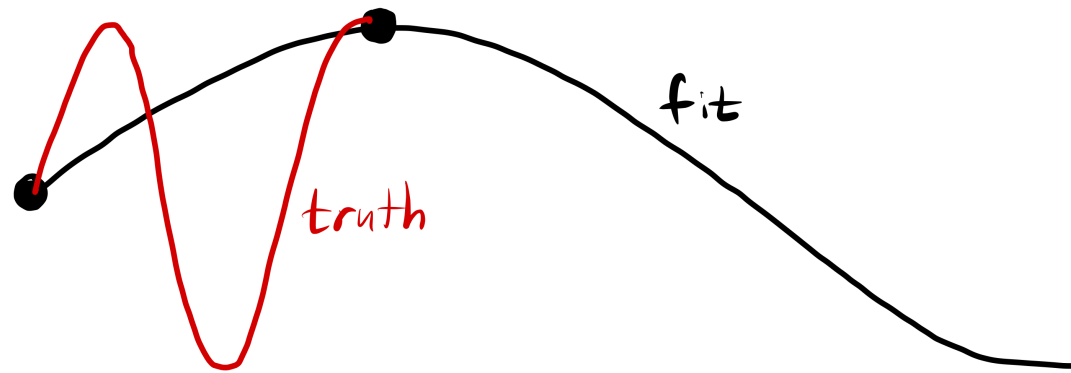
The usual approach to k, l

- S-transform on 3 profiles
 - A, φ vs m, z
- Assume $t_1=t_2=t_3$
- 3 estimates of λ_h projected onto 3 paths
 - k, l

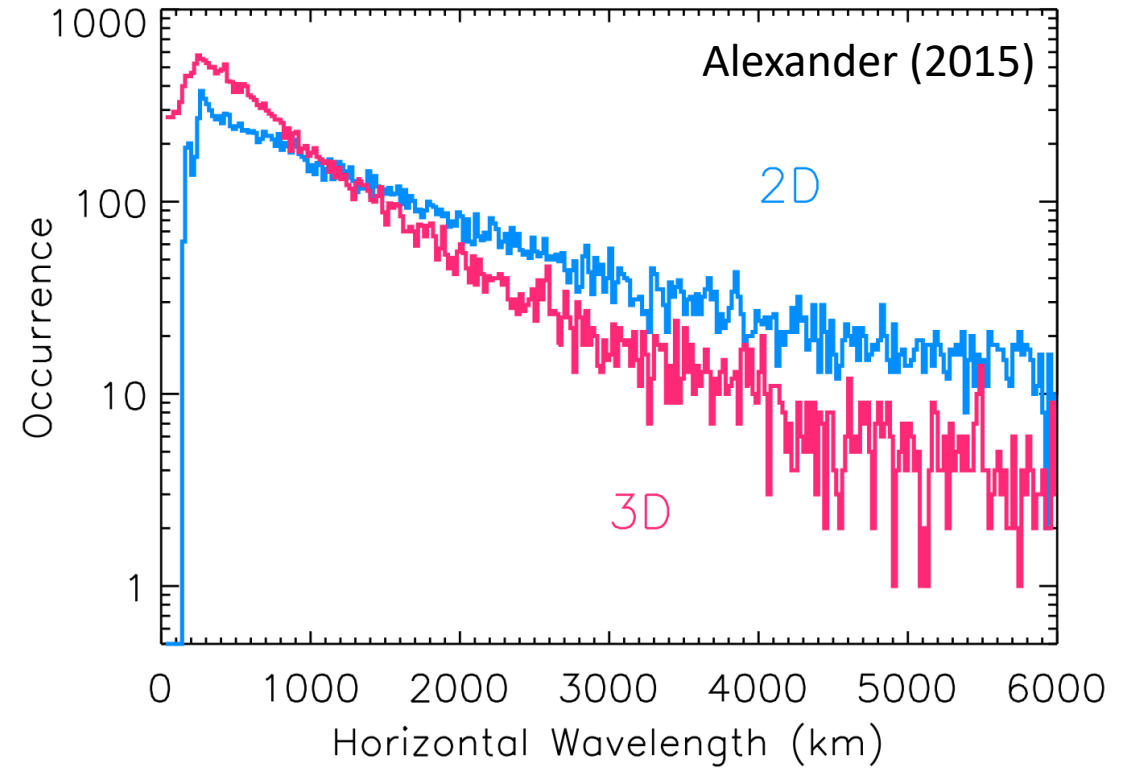
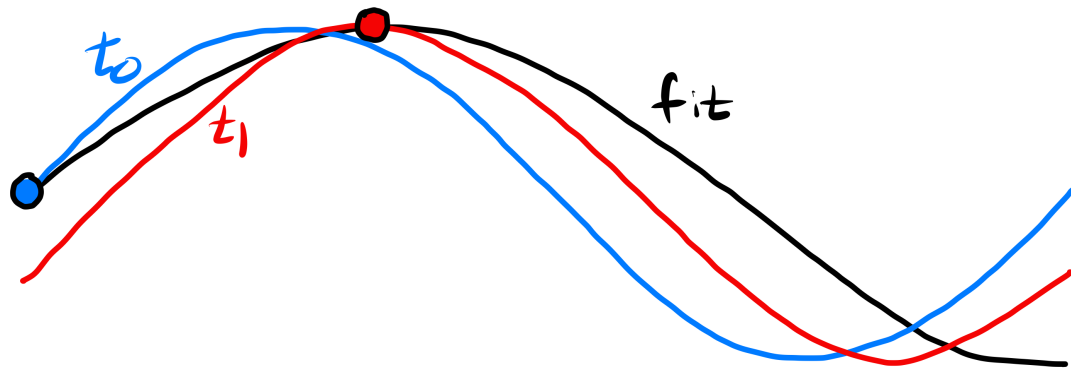


The trouble is...

It requires small Δx ...



...and small Δt .



Schmidt et al. (2016) uses early COSMIC-2

P. Alexander et al. (2018) defer

Alexander (2015) takes it with a grain of salt

The minimization approach

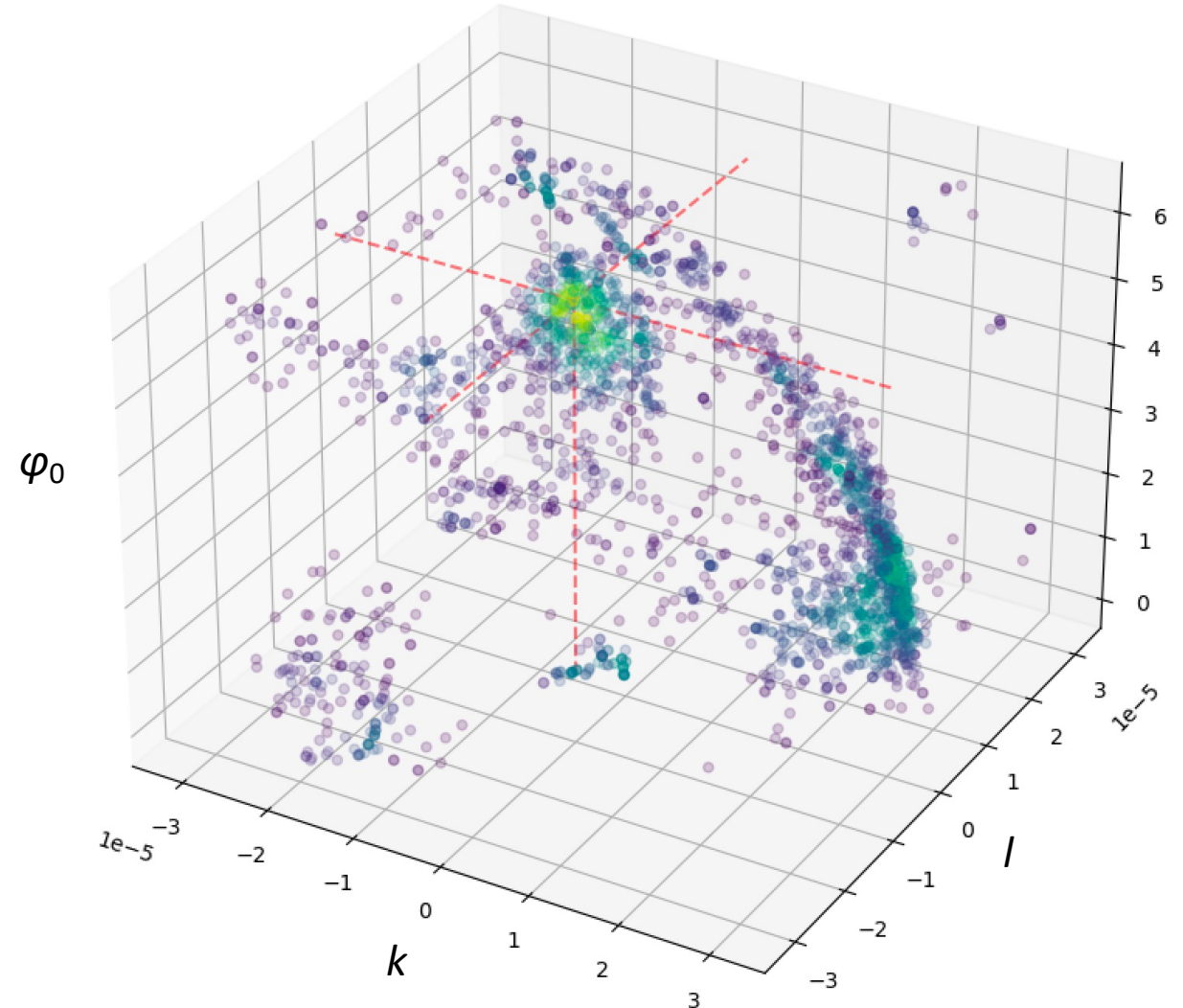
- Define $T'=T$ -background
- Assume $T' = A \cdot \Re\{\exp[i(kx + ly + mz - \nu t + \phi_0)]\} + \varepsilon$
- S-transform on dyads, *triads*, or tetrads
 - Determine A, m
- Let $\nu = \pm \sqrt{f^2 + N^2 \frac{k^2 + l^2}{m^2}}$
- Run MCMC ensemble sampler
 - Estimate $k, l, \varphi_0 \mid \nu > 0$
 - Estimate $k, l, \varphi_0 \mid \nu < 0$

Why MCMC Ensemble Sampler?

- Fewer calculations per profile
 - 10 walkers, 1000 steps = $\mathbf{O}10^4$ ($\times 2$)
 - $100 k_s \times 100 l_s \times 100 \varphi_{0,s} = \mathbf{O}10^6$ ($\times 2$)
- Explicit prior
 - Currently uninformed, i.e., uniform over
 - $|\lambda_x| > 200$ km
 - $|\lambda_y| > 200$ km
 - $\varphi_0 \in [0, 2\pi)$

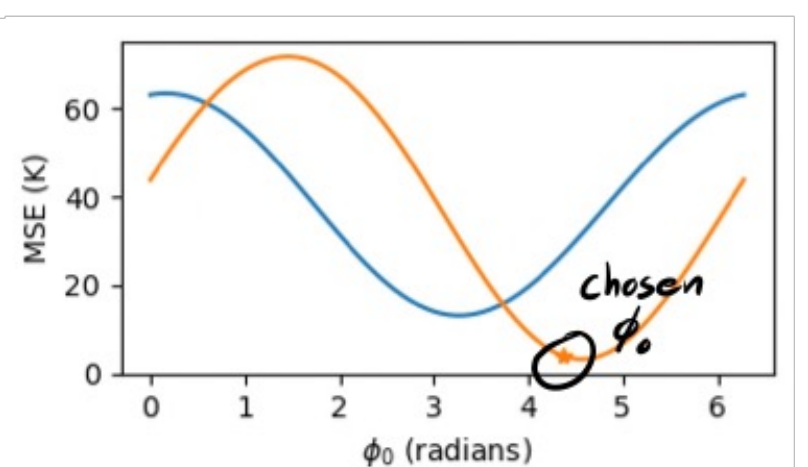
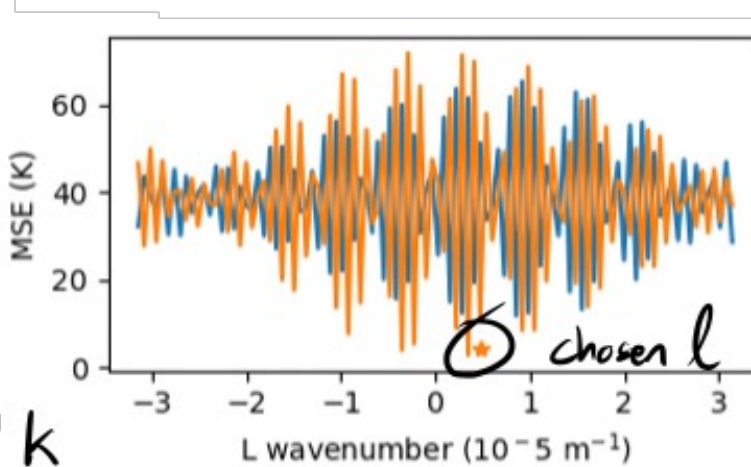
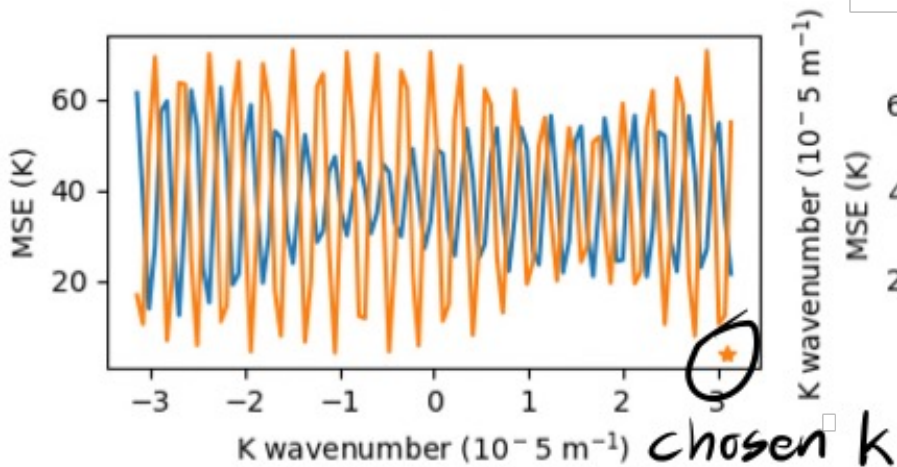
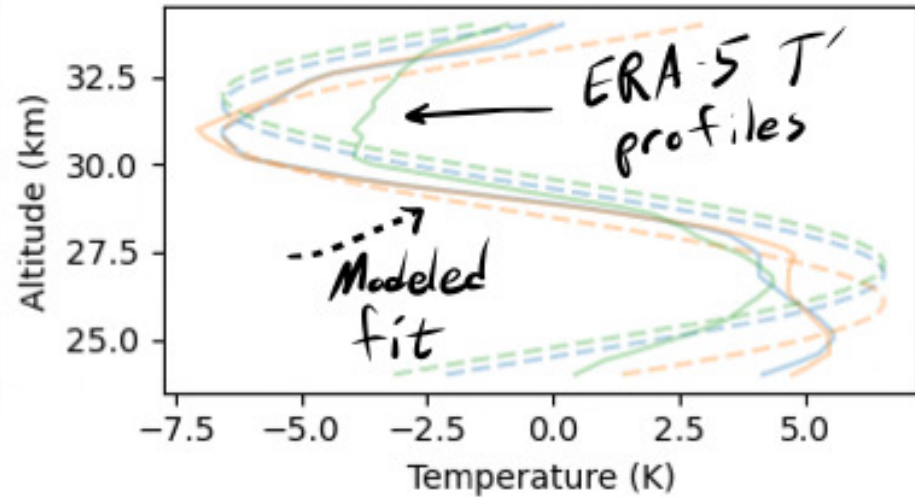
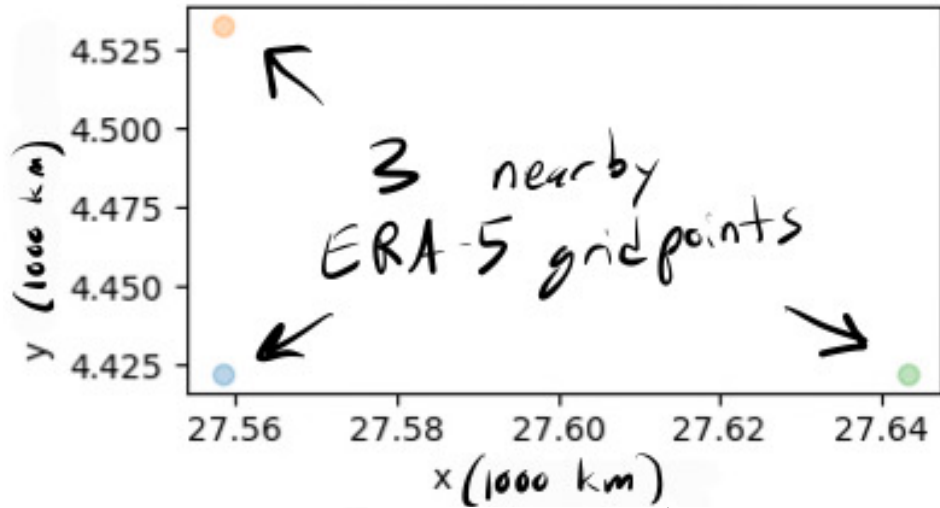
What to do with all those samples?

- Gaussian KDE, choose sample with largest density



- Sometimes it works well...

Sometimes it does poorly...

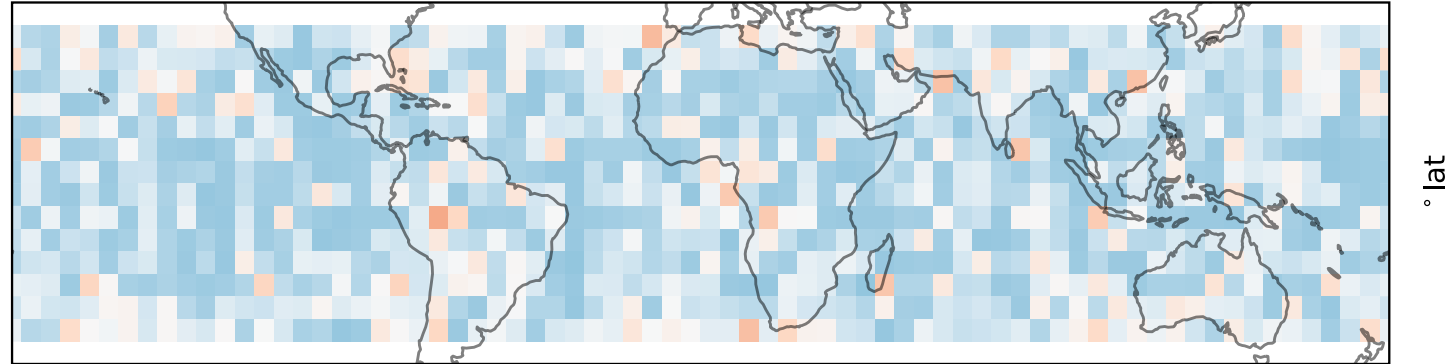


But...

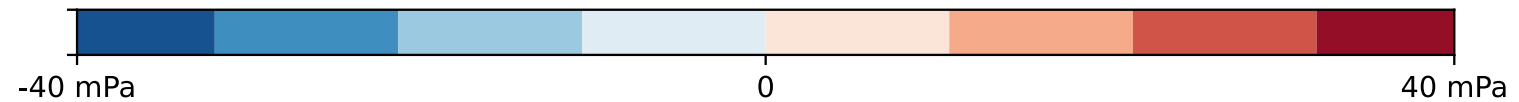
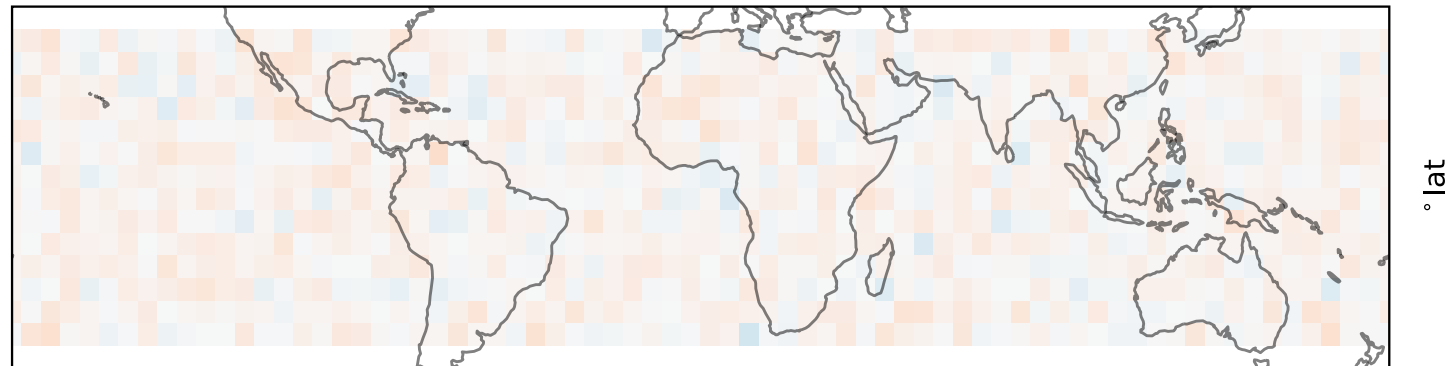
- The magnitude and direction of the calculated momentum flux is not *completely* random.

Data replaced by single, initialized wave everywhere

Eastward momentum flux should be about -2.2 mPa everywhere



Northward momentum flux should be about -0.3 mPa everywhere

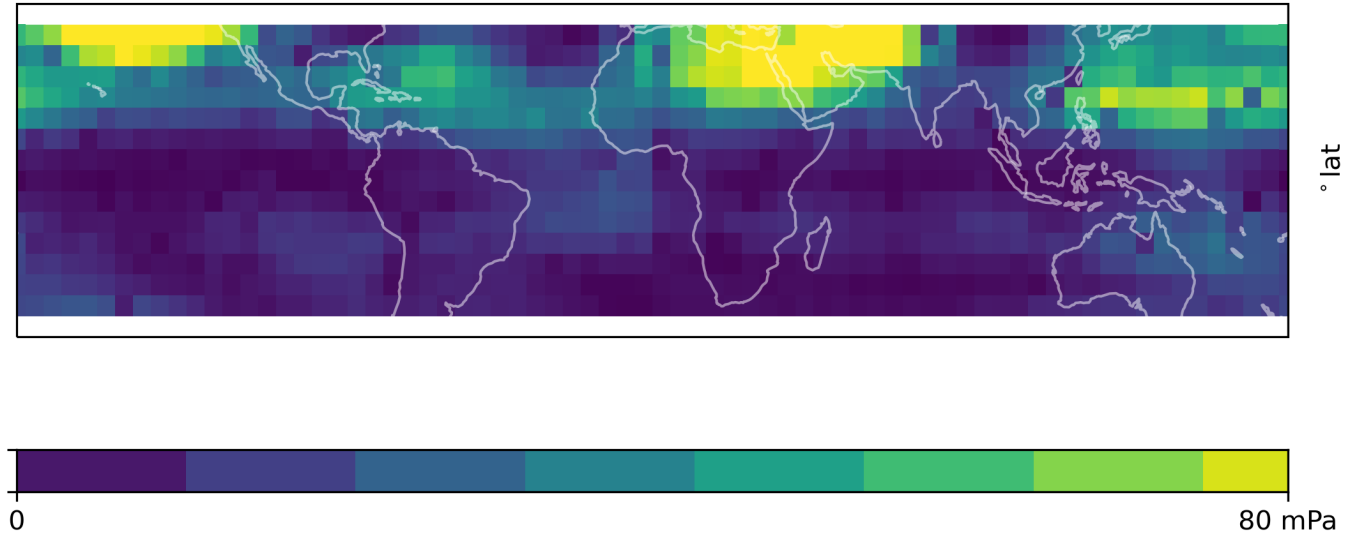


And...

- Magnitudes, though orders of magnitude too big, are *sometimes* big in the correct places.

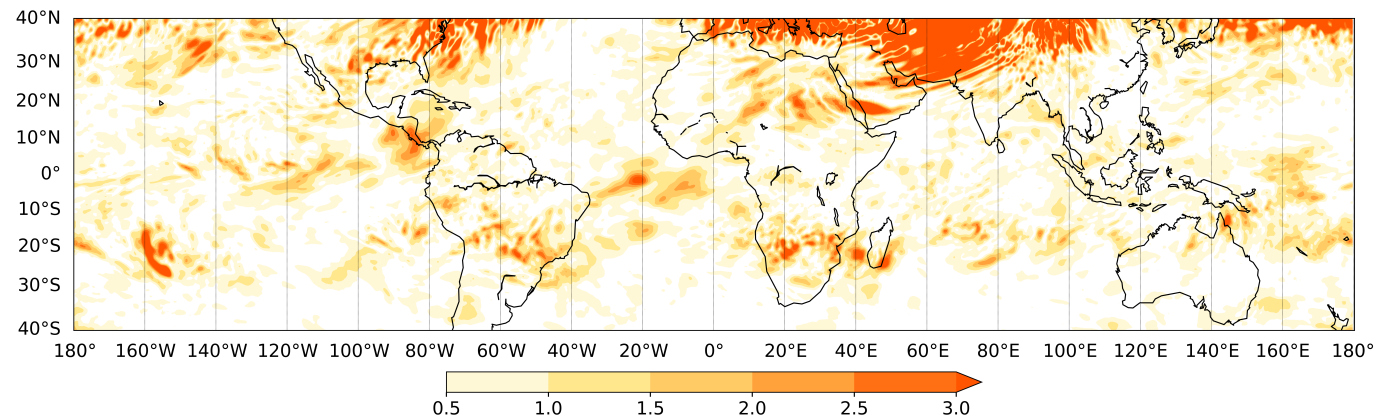
ERA-5 using minimization approach

(a) Absolute Momentum Flux @ 26 km, Dec 31 2020



Direct calculation by Pahlavan

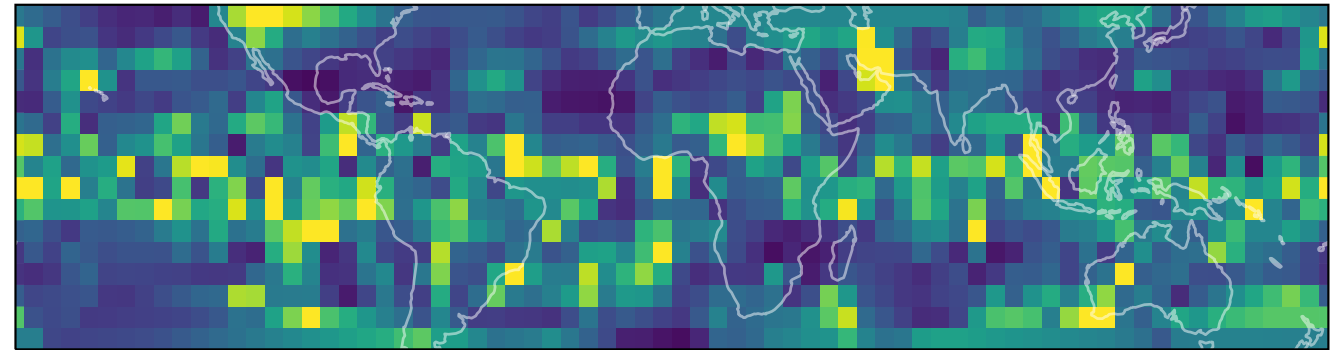
a) Absolute Momentum Flux



Sadly...

- Not ready for “prime time”
- Collocation requirements aren't as loose as I'd previously supposed

Flux calculated from GPS RO triads



So far...

- 2 months ago, I got junk
 - Poor treatment of φ_0
 - Too-discrete S-transform
- Now I'm still getting junk
 - With some basis in reality
 - MCMC approach provides several ways forward

Ways forward

- Check again that pathological result isn't the result of a bug
- Analyze tetrads - perhaps feasible now
- Improving the prior
 - Explicitly favor lower k, l
 - Downward c_z
 - Upward c_{gz}
 - Incorporate ERA-5...
 - ...just a little: c_x dependency on U_{trop}
 - ...a whole lot: calculate prior distribution from surrounding ERA5 data
- Incorporate varying lon, lat, time versus height of RO profile
- Incorporate N' or background U (doppler shift) into objective function

What about balloons?

2 RO + 1 HVRRD

- Slow ascent rates are an advantage
- Wind profile can be incorporated directly into objective function
- Varying coverage, burst height

1 or 2 RO + 1 “Strateole”

- Horizontal flight path compliments GPS RO
- Winds, again, can be incorporated directly into objective function
- Rare

Thank you!

- Bill Randel
- Bill Kuo
- Bill Schreiner
- Fei Wu



- Joan Alexander
- Martina Bramberger



- Travis O'Brien
- Kaj Johnson



- Hamid Pahlavan

