

Combining Uncertainty Quantification and XAI to Understand the Sensitivities of Deep Learning Winter Precipitation Type Predictions

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Verification Workshop
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Motivation



<https://avgeekery.com/ice-ice-baby-pilots-deal-winty-mess/>



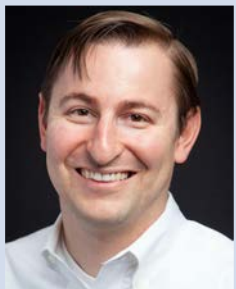
militarynews.com

- Transitions between liquid and frozen precipitation types can greatly impact transportation and logistics
- Forecasting p-type transitions is particularly challenging due to uncertainties in
 - thermodynamics
 - NWP models
 - observations
- ML methods with predictive uncertainty can help us understand and utilize uncertainty quantification (UQ) for more robust p-type forecasts
- Goals:
 - Introduce evidential deep learning
 - Connect uncertainty estimates with physical features
 - Link predictions to input features with XAI

Paper in prep: Evidential Deep Learning: Enhancing Predictive Uncertainty Estimation for Earth System Science Applications

The NCAR Machine Integration and Learning for Earth Systems (MILES) Group

MILES Core



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Belen Saavedra Rios
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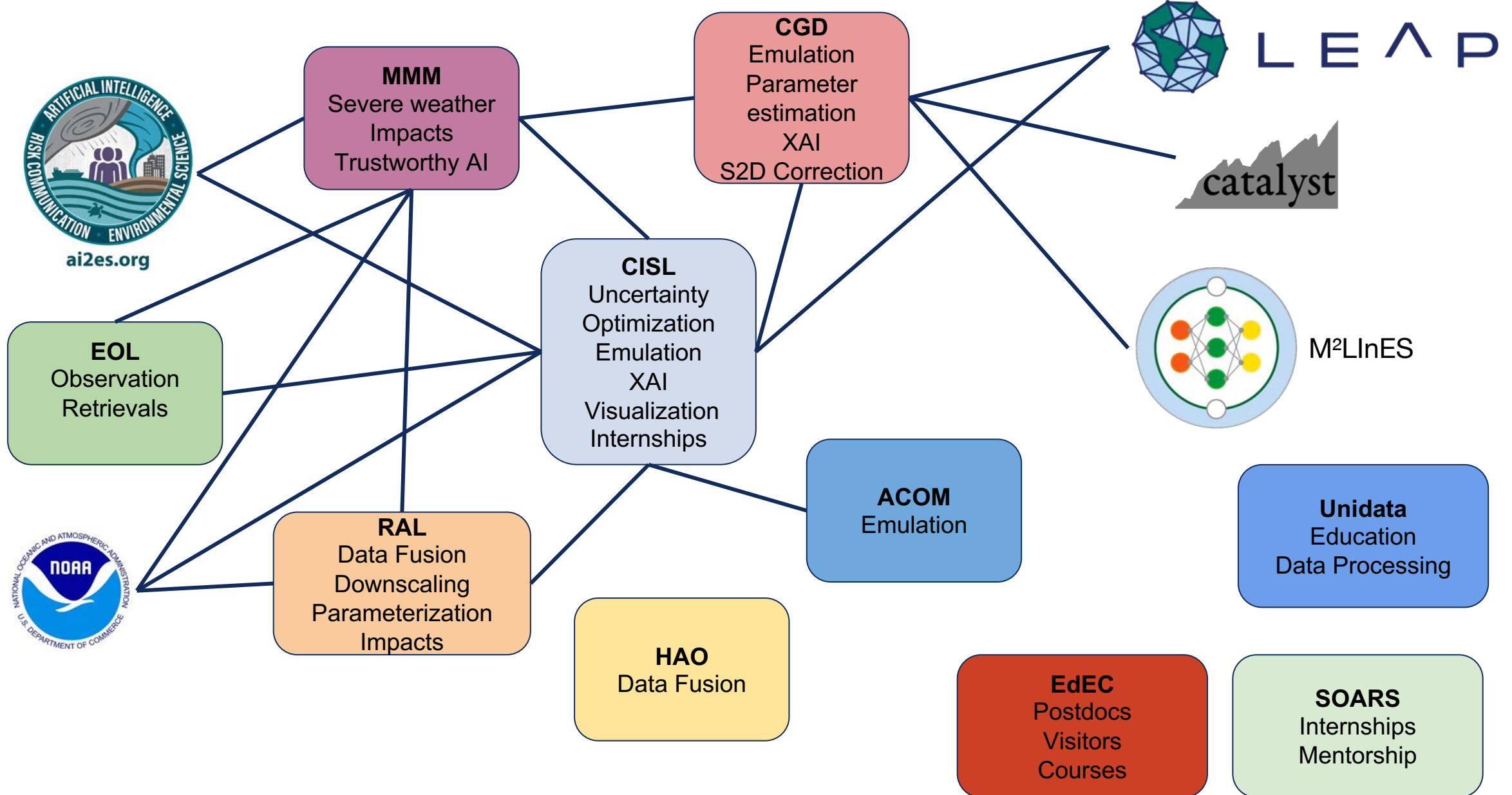


Da Fan
Visitor
Penn State

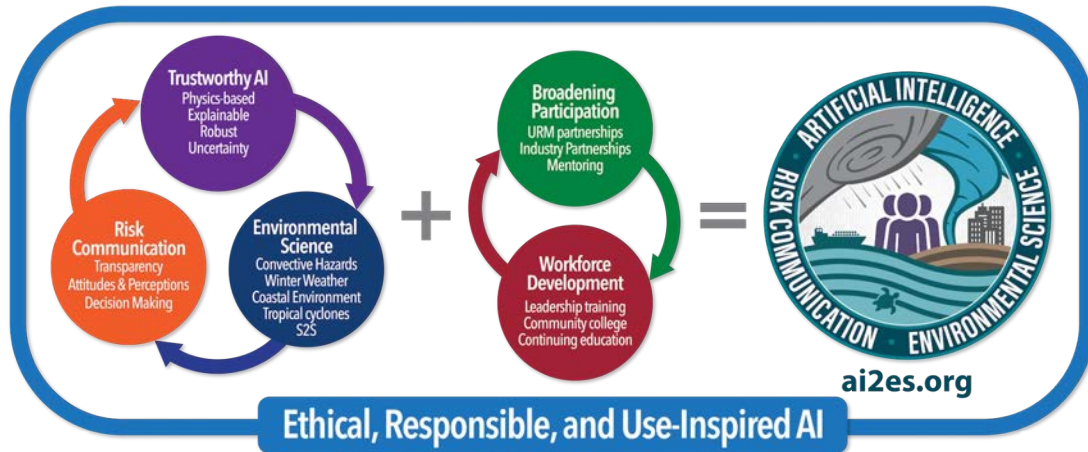
Bill Petzke
Software Engineer III,
RAL

MILES+

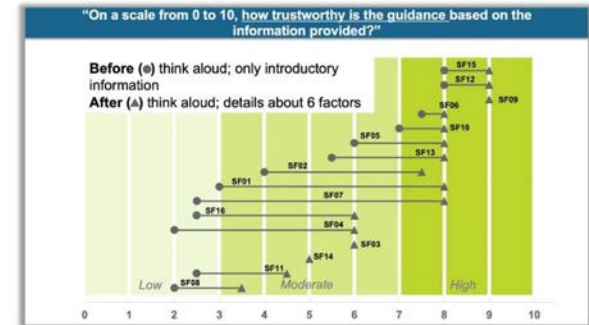
The NCAR/UCAR AI Web



AI2ES: Developing Trustworthy AI Systems with User and Domain Expert Guidance



Assessing the Trustworthiness of AI/ML Forecast Guidance



Inductive analysis of reasoning/justification of forecasters' trustworthiness rating

Trustworthiness	Before Think Aloud	After Think Aloud
Low (0-3)	<ul style="list-style-type: none"> don't know enough about model no experience with model no model verification 	N/A
Moderate (4-6)	<ul style="list-style-type: none"> made sense climatologically model matches conceptual model output looks realistic 	<ul style="list-style-type: none"> additional background information familiarity with input data sources (e.g., WRF, HREF) comparison to conventional resources (e.g., SPC)
High (7-10)	<ul style="list-style-type: none"> meteorologically valid models used well known resources operational utility of storm mode guidance 	<ul style="list-style-type: none"> developers' operational and domain expertise reputations of the developers' institutions

Forecasters need to personally use a model or piece of guidance over time to build trust in it.

mgcains@ucar.edu



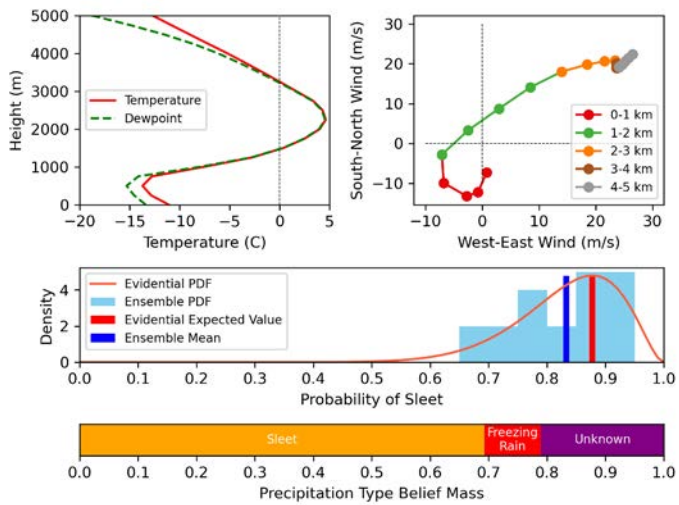
Vision: AI2ES is developing *novel, physically based AI techniques* that are demonstrated to be *trustworthy*, and will directly improve *prediction, understanding, and communication* of high-impact weather and climate hazards.

CISL: David John Gagne, John Schreck, Charlie Becker, Gabrielle Gantos

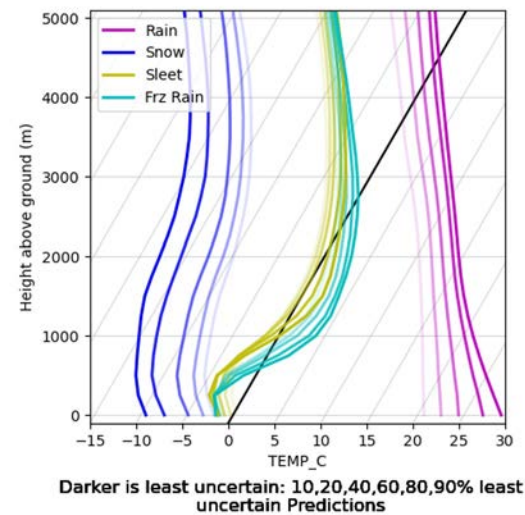
MMM: Julie Demuth, Chris Wirz, Mariana Cains

RAL: Bill Petzke

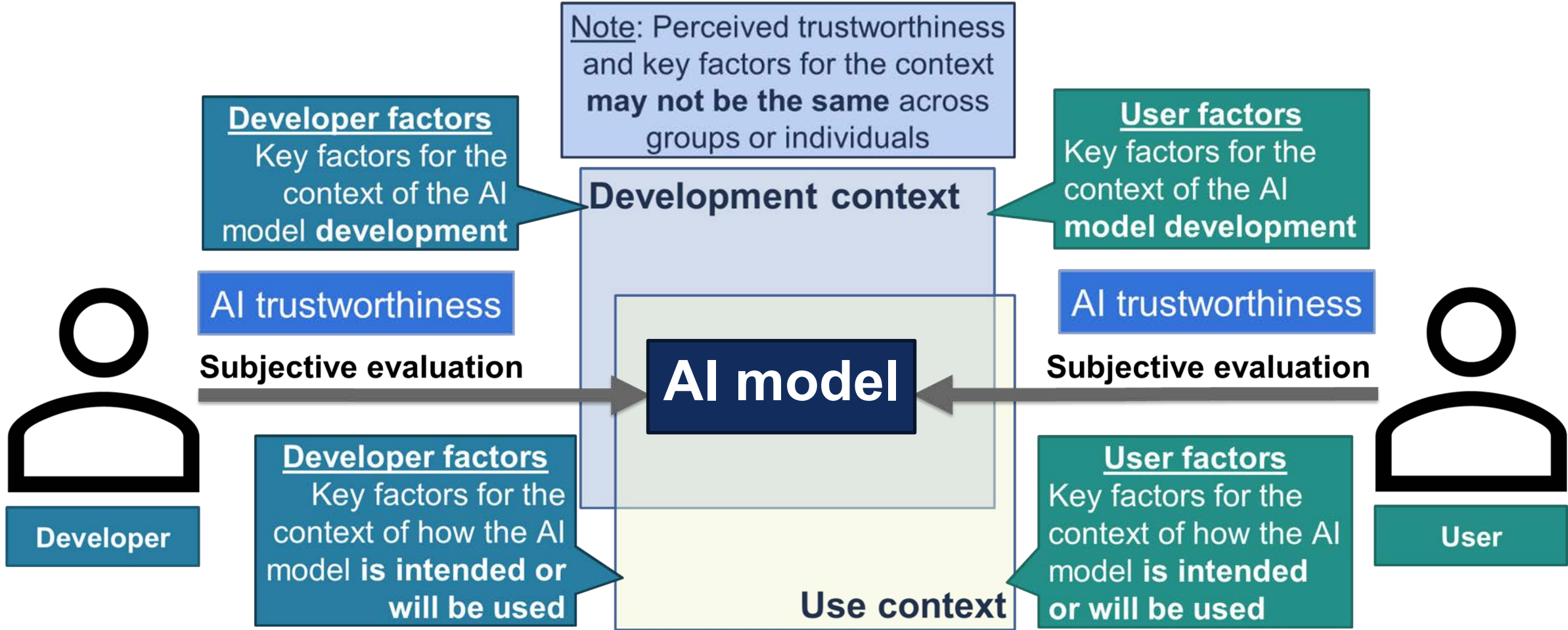
Unidata: Thomas Martin



Median Soundings by Evidential Uncertainty



Our reconceptualization of trustworthy AI as **perceptual**

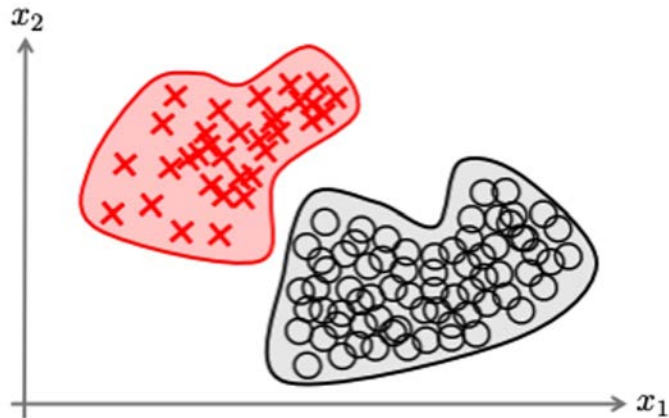


Wirz et al. 2023, (Re)Conceptualizing trustworthy AI: A foundation for change, In Prep.



Decomposition of Uncertainty

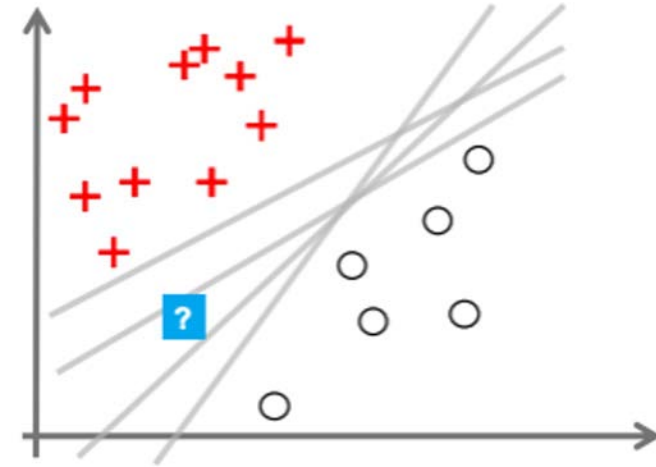
Aleatoric Uncertainty



Definition: Uncertainty from unexplained variation in the data.

Estimated by: Single probabilistic AI model.

Epistemic Uncertainty



Definition: Uncertainty from variation in model predictions.

Estimated by: Ensemble of deterministic AI models.

Total Uncertainty

Definition: Combined aleatoric and epistemic uncertainty.

Estimated by:

- 1) Ensemble of probabilistic AI models
- 2) Single “evidential” (higher-order probabilistic) AI model
- 3) Bayesian AI models

Collaborators

John Schreck, Charlie Becker, Gabrielle Gantos, Julie Demuth, Chris Wirz, Jacob Radford, Nick Bassil, Kara Sulia, Chris Thorncroft, Amy McGovern, Eliot Kim, Justin Willson, Kim Elmore, Maria Molina

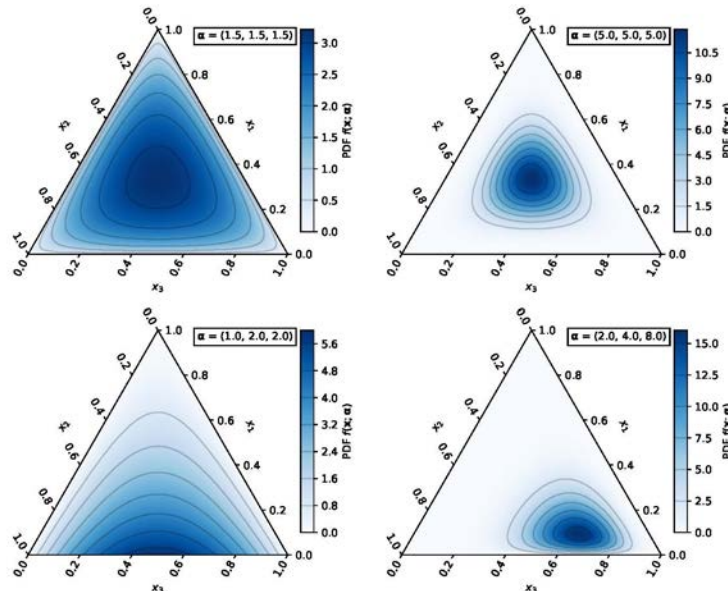


Dirichlet Distribution: Model Classification Epistemic Uncertainty

$$\begin{aligned}\boldsymbol{\alpha} &= (\alpha_1, \dots, \alpha_K) = \text{concentration hyperparameter} \\ \mathbf{p} \mid \boldsymbol{\alpha} &= (p_1, \dots, p_K) \sim \text{Dir}(K, \boldsymbol{\alpha}) \\ \mathbb{X} \mid \mathbf{p} &= (\mathbf{x}_1, \dots, \mathbf{x}_K) \sim \text{Cat}(K, \mathbf{p})\end{aligned}$$

then the following holds:

$$\begin{aligned}\mathbf{c} &= (c_1, \dots, c_K) = \text{number of occurrences of category } i \\ \mathbf{p} \mid \mathbb{X}, \boldsymbol{\alpha} &\sim \text{Dir}(K, \mathbf{c} + \boldsymbol{\alpha}) = \text{Dir}(K, c_1 + \alpha_1, \dots, c_K + \alpha_K)\end{aligned}$$



Theory of Evidence and Subjective Logic

How can we summarize epistemic uncertainty more effectively?

Classification probabilities must sum to 1, but what if we removed that restriction?

Subjective logic (SL) formulates *belief* b_k over K classes, plus u or “**I don't know**”, as a Dirichlet distribution (prior). For a NN with K outputs

$$u + \sum_{k=1}^K b_k = 1$$

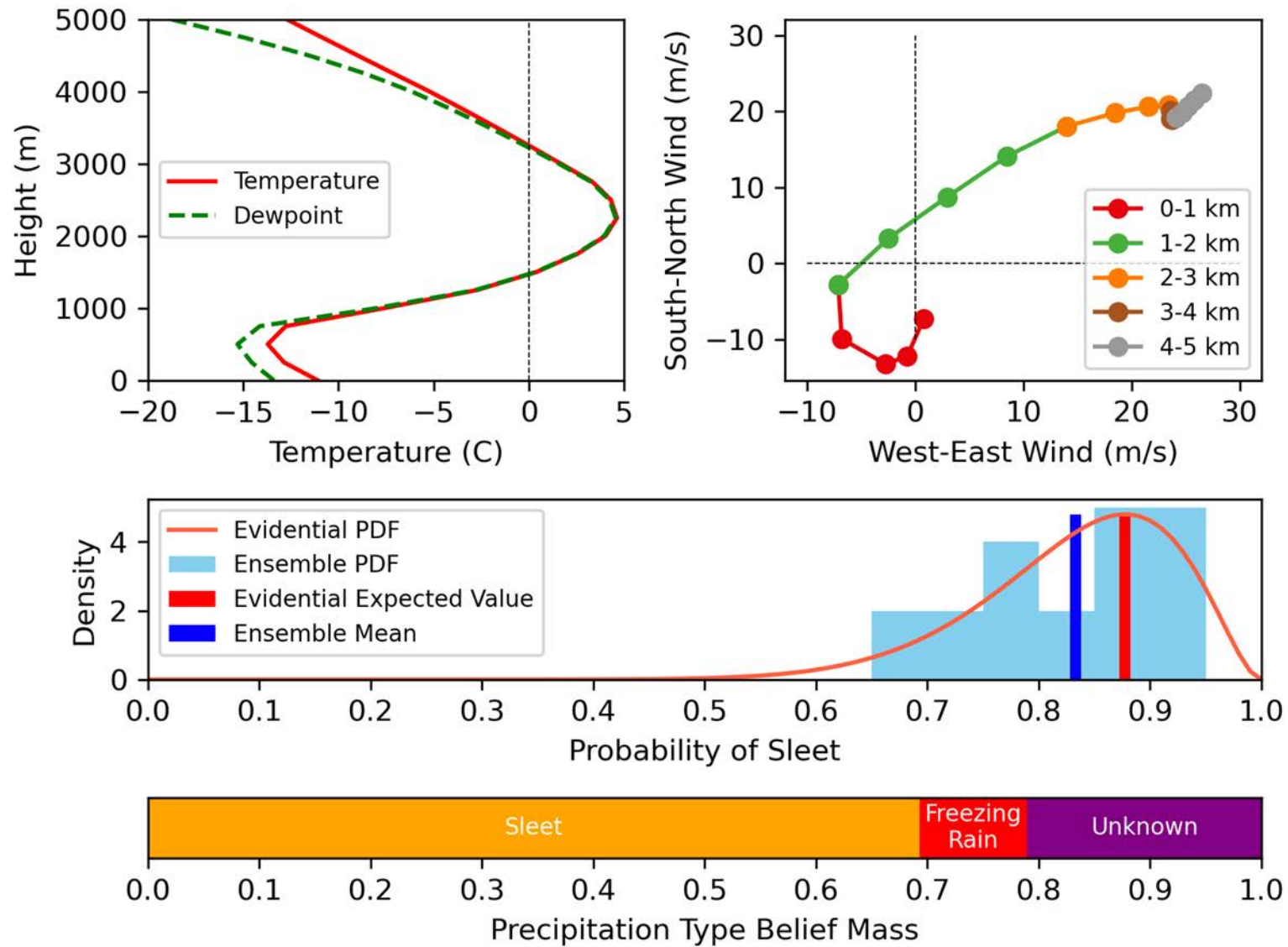
where b_k is the belief mass, which is the normalized sum of evidence for an outcome.

Each b_k is defined as

$$b_k = \frac{e_k}{S} \quad \text{where} \quad S = \sum_{i=1}^K (e_i + 1) \quad \text{and thus} \quad u = \frac{K}{S}$$

Dirichlet distributions can be updated based on adding new evidence to each outcome.

Evidential Deep Learning



Full Classifier Evidential Loss

$$\mathcal{L}(\Theta) = \sum_{i=1}^N \mathcal{L}_i(\Theta) + \lambda_t \sum_{i=1}^N KL[D(\mathbf{p}_i | \tilde{\alpha}_i) || D(\mathbf{p}_i | \langle 1, \dots, 1 \rangle)],$$

MLE Loss

Distance from 0-evidence/uniform prior

Annealing coefficient $\lambda_t = \min(1.0, t/50)$ | $\tilde{\alpha} = \mathbf{y}_i + (1 - \mathbf{y}_i) \odot \alpha$ Alphas of misleading evidence

MLE Loss

$$\mathcal{L}_i(\Theta) = \int \|\mathbf{y}_i - \mathbf{p}_i\|_2^2 \frac{1}{B(\alpha_i)} \prod_{j=1}^K p_{ij}^{\alpha_{ij}-1} d\mathbf{p}_i = \sum_{j=1}^K (y_{ij} - \hat{p}_{ij})^2 + \frac{\hat{p}_{ij}(1 - \hat{p}_{ij})}{(S_i + 1)}$$

MSE

Variance

Distance
from 0-
evidence
prior

$$KL[D(\mathbf{p}_i | \tilde{\alpha}_i) || D(\mathbf{p}_i | \mathbf{1})] = \log \left(\frac{\Gamma(\sum_{k=1}^K \tilde{\alpha}_{ik})}{\Gamma(K) \prod_{k=1}^K \Gamma(\tilde{\alpha}_{ik})} \right) + \sum_{k=1}^K (\tilde{\alpha}_{ik} - 1) \left[\psi(\tilde{\alpha}_{ik}) - \psi \left(\sum_{j=1}^K \tilde{\alpha}_{ij} \right) \right],$$

Pushes incorrect alphas toward 1 (uniform distribution)

Dirichlet Aleatoric and Epistemic Uncertainties

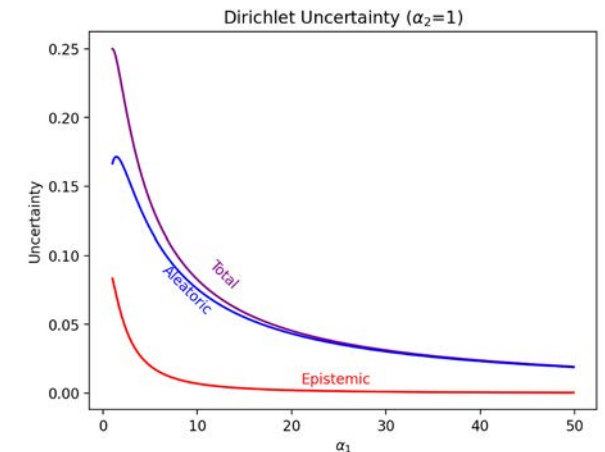
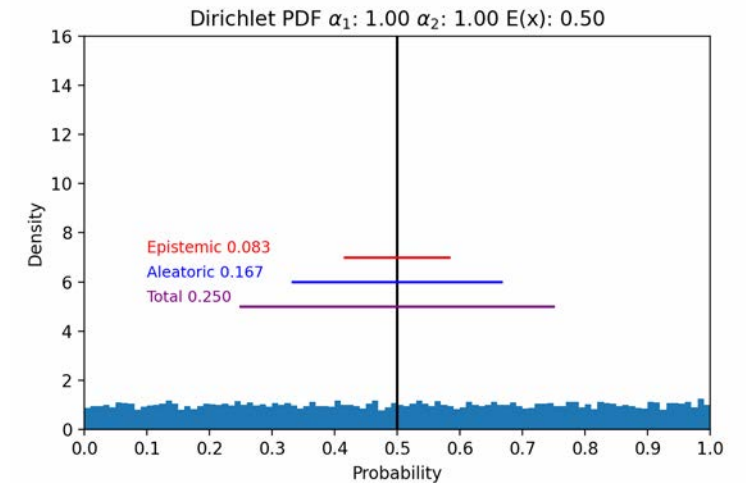
Law of total variance decomposes the total uncertainty into the sum of the unexplained variance plus the explained variance:

$$\text{Var}(y_j) = \mathbb{E}(\text{Var}(y_j|\mathbf{p})) + \text{Var}(\mathbb{E}(y_j|\mathbf{p}))$$

$$\begin{aligned} \text{Aleatoric (unexplained)} &= \mathbb{E}\{\text{Var}(y_j|\mathbf{p})\} = \mathbb{E}\{p_j(1-p_j)\} \\ &= \mathbb{E}(p_j) - \mathbb{E}(p_j^2) \\ &= \mathbb{E}(p_j) - \{\mathbb{E}(p_j)\}^2 - \text{Var}(p_j) \\ &= \frac{\alpha_j}{S} - \left(\frac{\alpha_j}{S}\right)^2 - \frac{\alpha_j}{S} \left(1 - \frac{\alpha_j}{S}\right) \end{aligned}$$

$$\begin{aligned} \text{Epistemic (explained)} &= \text{Var}\{\mathbb{E}(y_j|\mathbf{p})\} = \text{Var}(p_j) \\ &= \frac{\alpha_j}{S} \left(1 - \frac{\alpha_j}{S}\right) \end{aligned}$$

Total = Aleatoric + Epistemic



Probabilistic Forecast Example: Classifying Winter Precipitation Type

Data

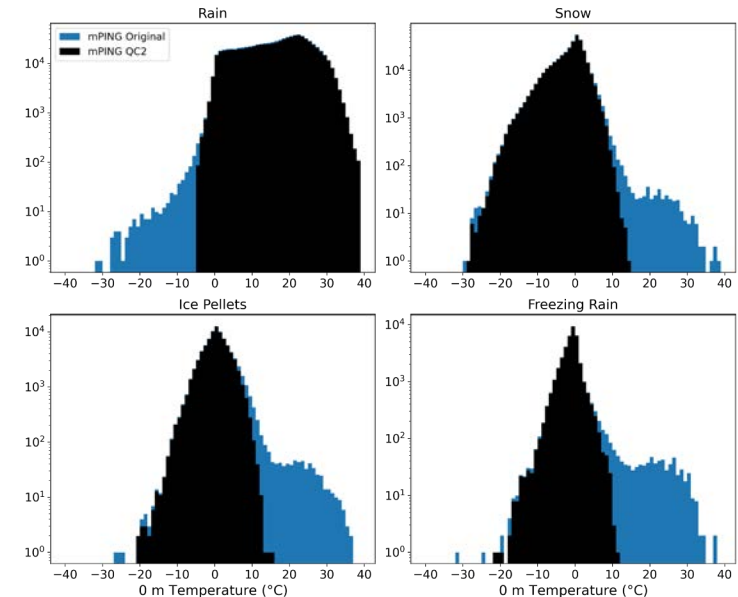
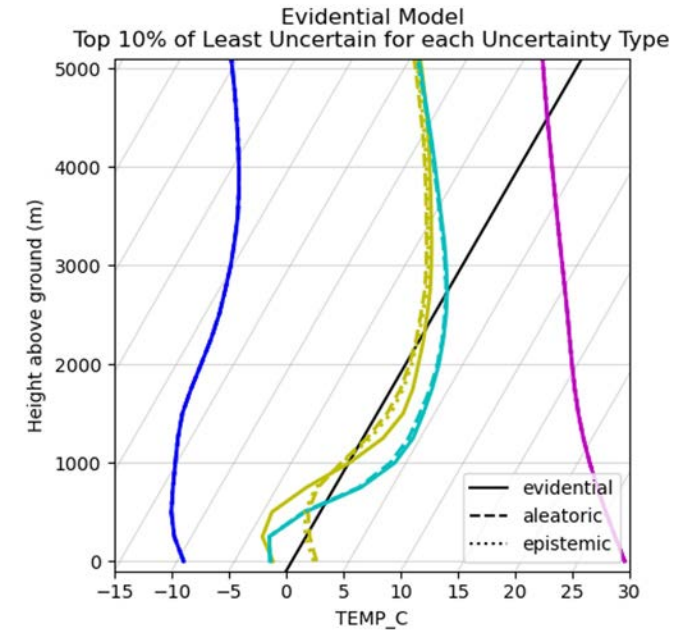
- NOAA Rapid Refresh Vertical Profiles
- Interpolate from pressure to height coords

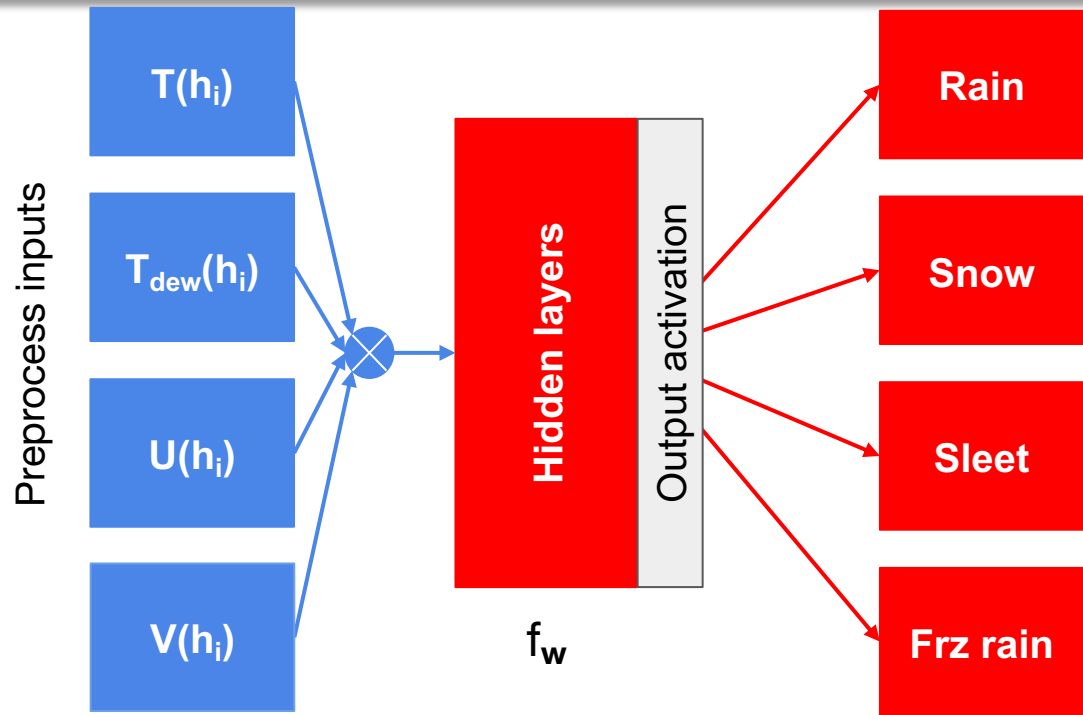
Input (0 - 5 km above surface, every 250 meters)

- Temperature, Dewpoint, U-Wind, V-Wind

Target

- mPING Crowd-sourced reports of winter precipitation types
 - *Rain, Snow, Sleet, Freezing Rain*





(i) Deterministic:

Predict probabilities for classes

Loss = Cross-entropy

$$p_k = \text{Softmax}(f_w(T, T_{\text{dew}}, U, V))_k$$

(ii) Evidential:

Predict evidence for classes

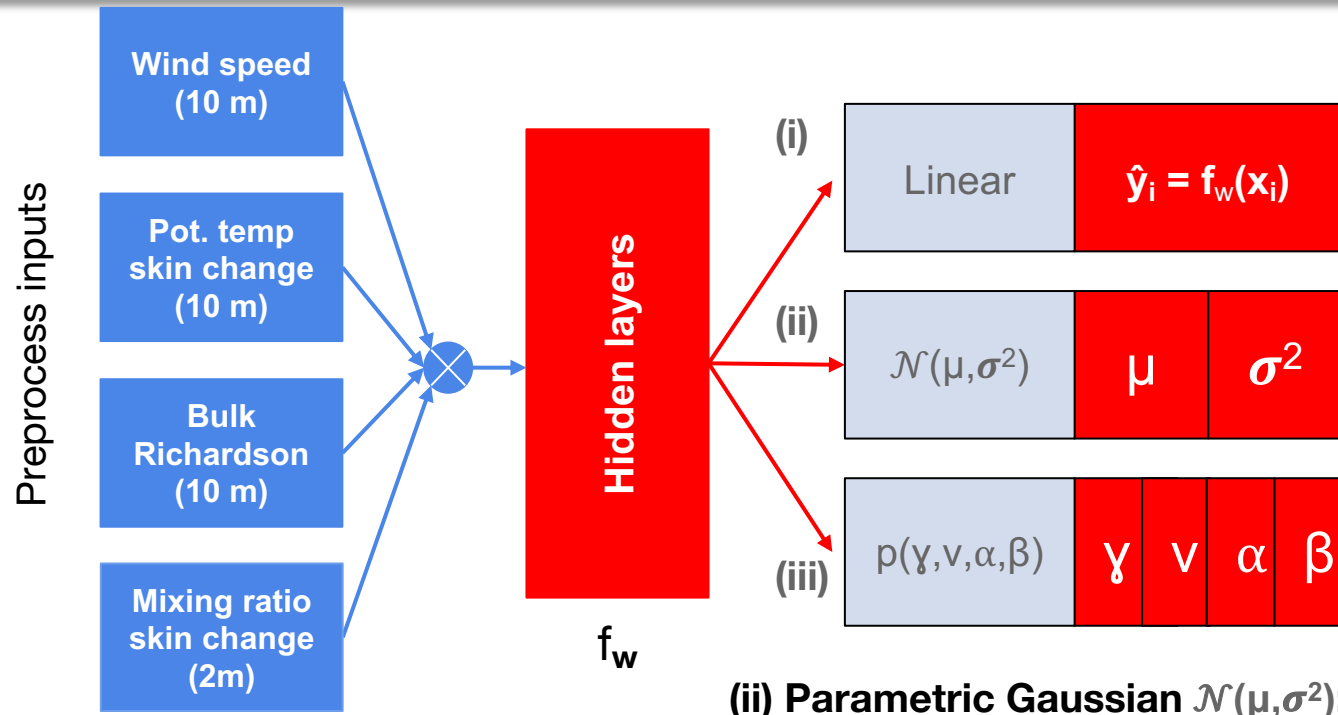
Loss = Evidential

$$e_k = \text{ReLU}(f_w(T, T_{\text{dew}}, U, V))_k$$

$$\alpha_k = e_k + 1$$

Compute S, evidential u, and the probabilities p_k

(a) P-type (categorical problem)



(i) Deterministic:

Predict values for the defined tasks

Loss = RMSE/MAE/etc

Number of outputs = number of tasks

(iii) Parametric Normal-Inverse Gamma $p(\gamma, v, \alpha, \beta)$:

Predict evidence for parameters for each task

Loss = Evidential, Number of outputs = 4 * number of tasks

Post-prediction: Compute mean, aleatoric, and epistemic uncertainties

(b) Surface layer (regression problem)

(ii) Parametric Gaussian $\mathcal{N}(\mu, \sigma^2)$:

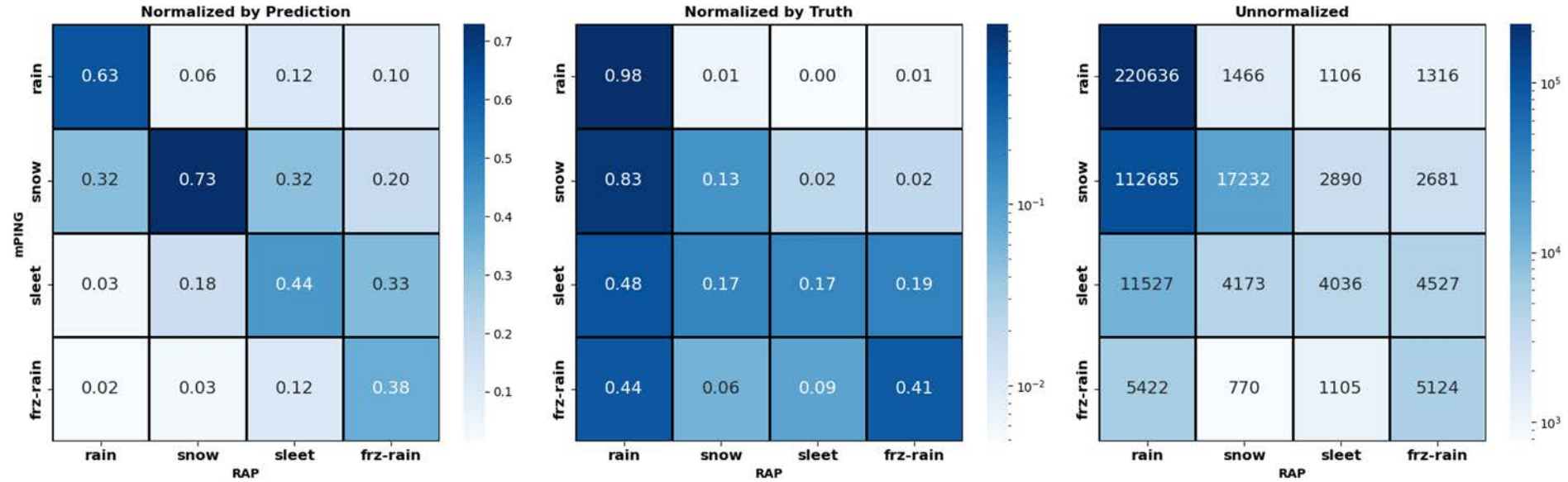
Predict the mean and variance for each task

Loss = NLL

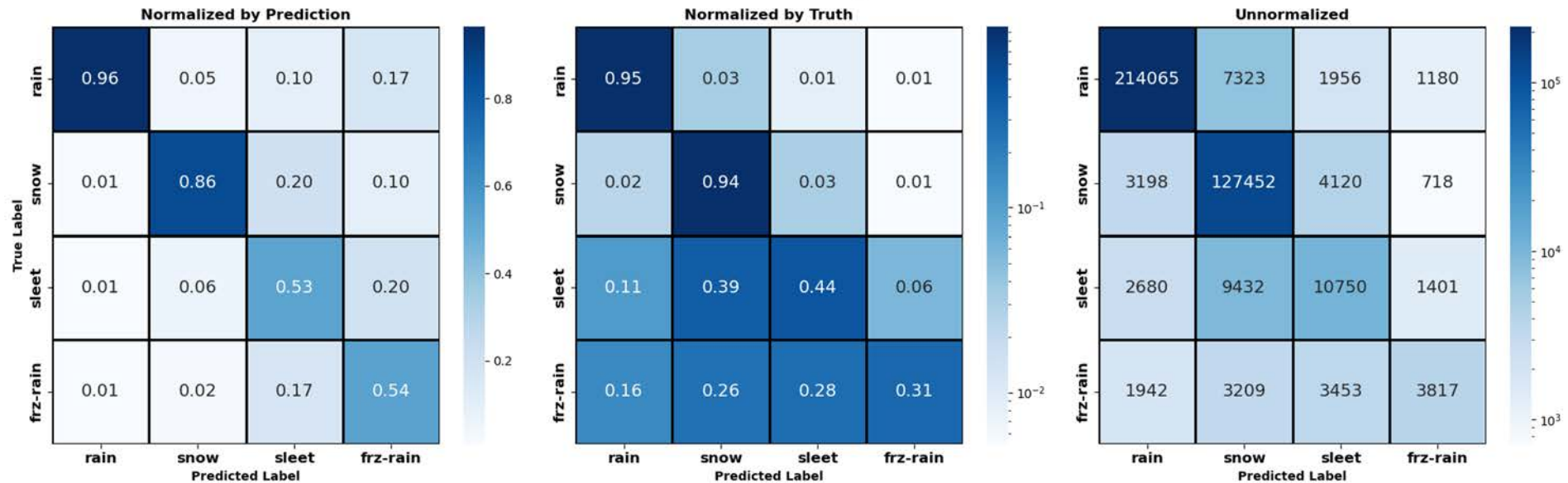
Number of outputs = 2 * number of tasks

Precipitation-Type Validation

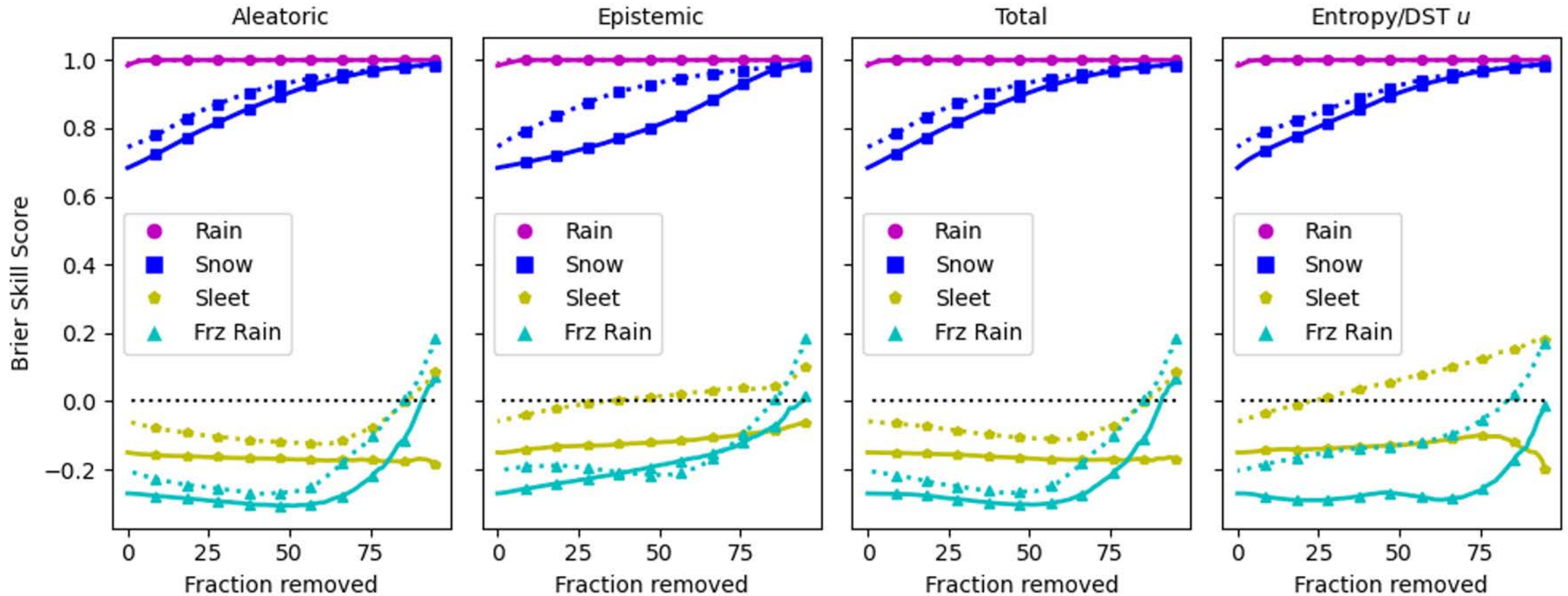
mPING vs RAP



Evidential Unweighted



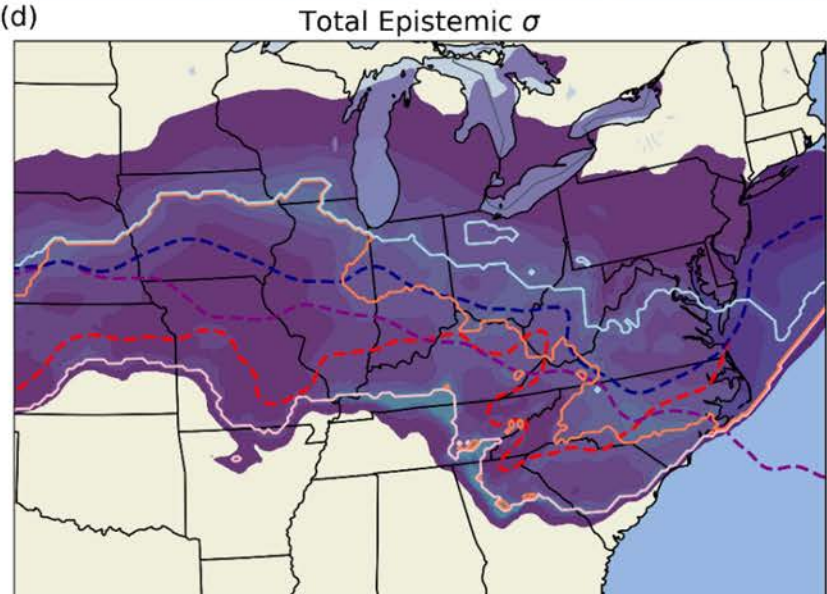
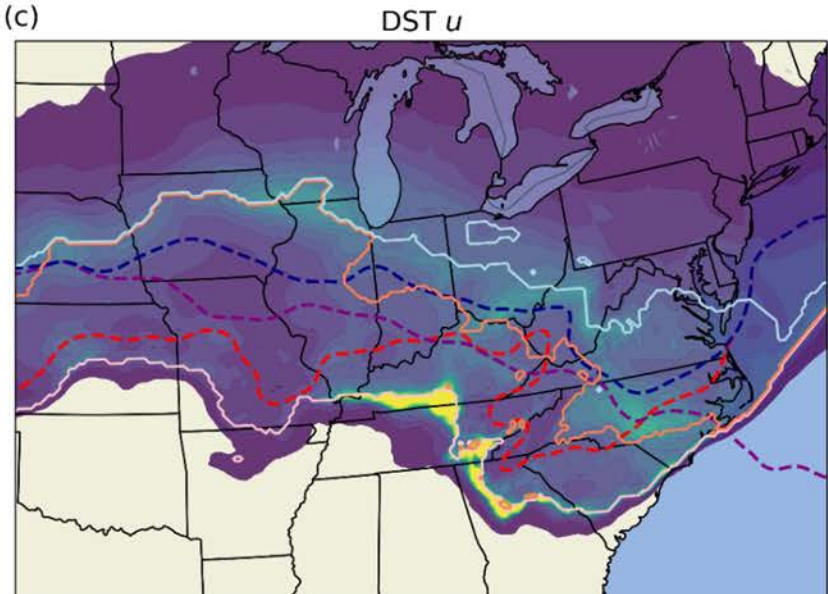
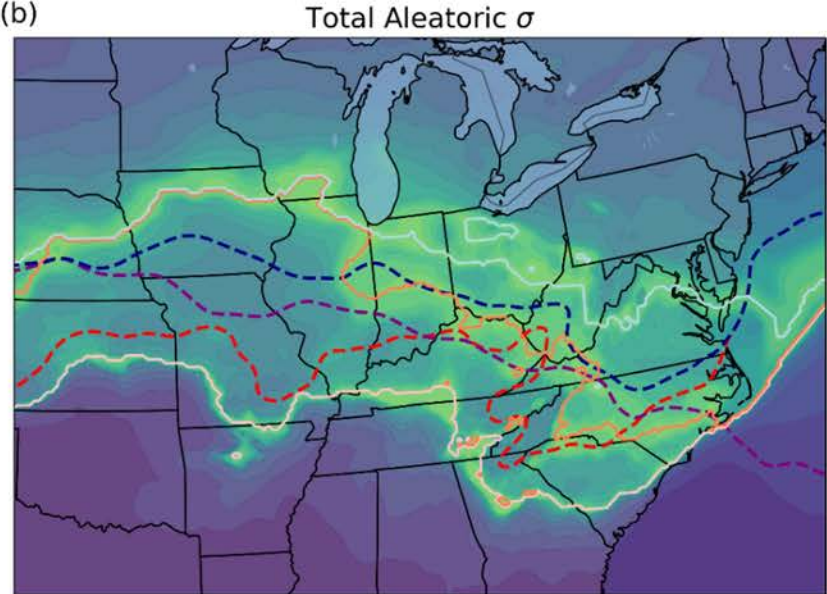
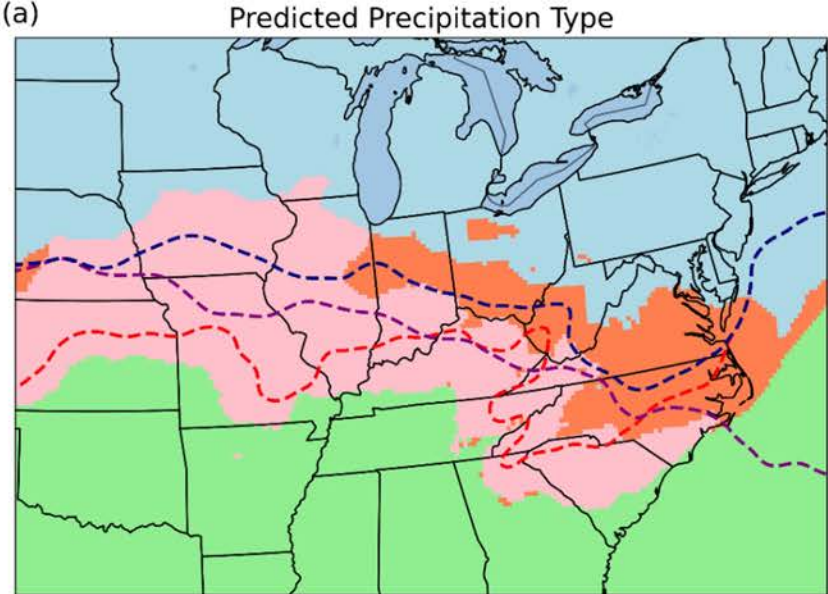
P-type Drop Fraction



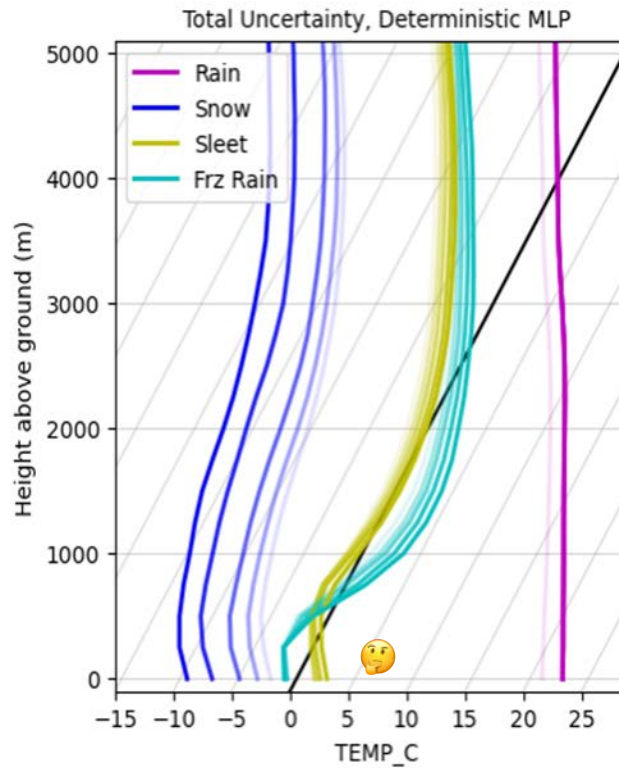
How well does each type of uncertainty discriminate between easier and harder to classify events?

Regional Case Study

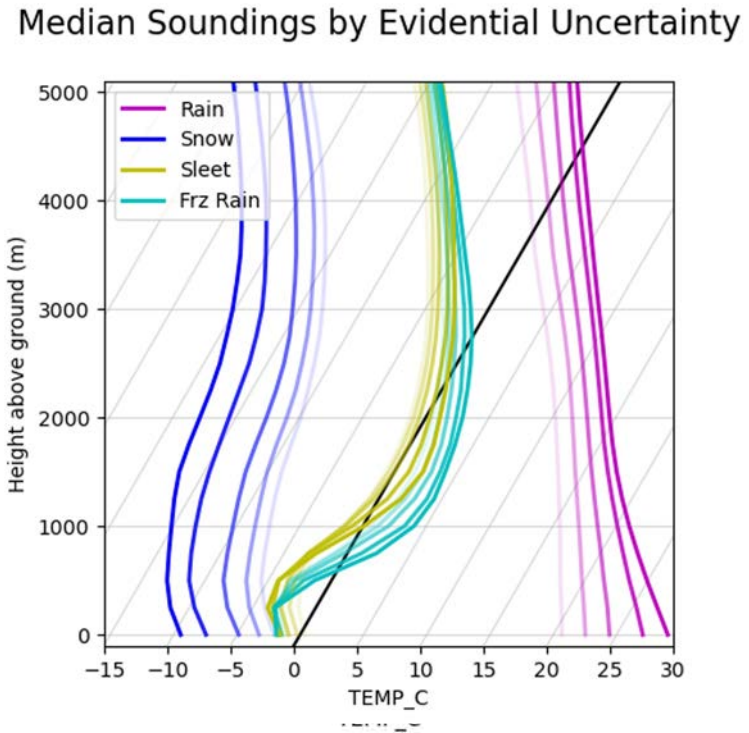
Evidential Precipitation Type Uncertainties Valid 2016-12-17-0000 UTC



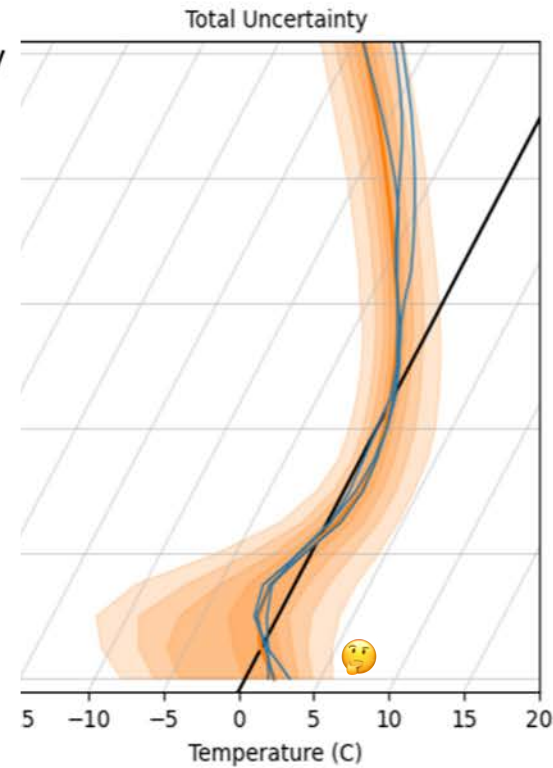
Evaluation: Binned by Uncertainty



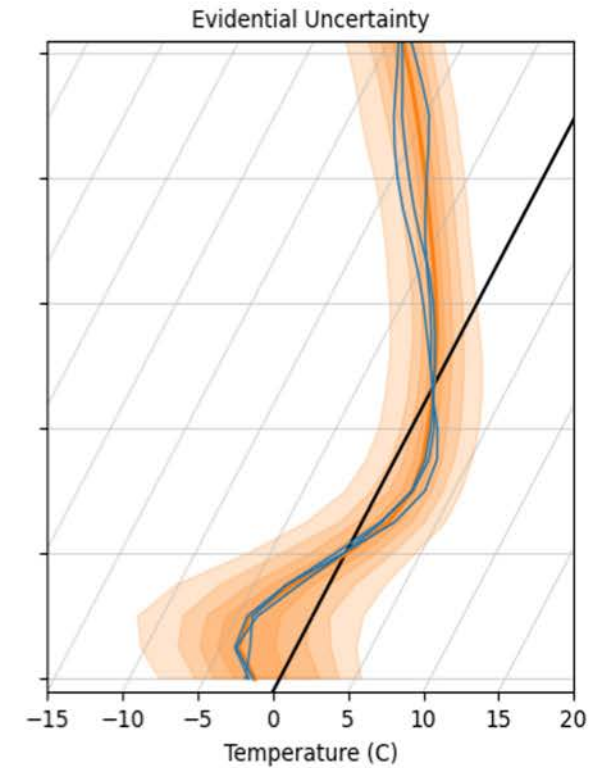
MLP with Monte Carlo Dropout



Evidential Model



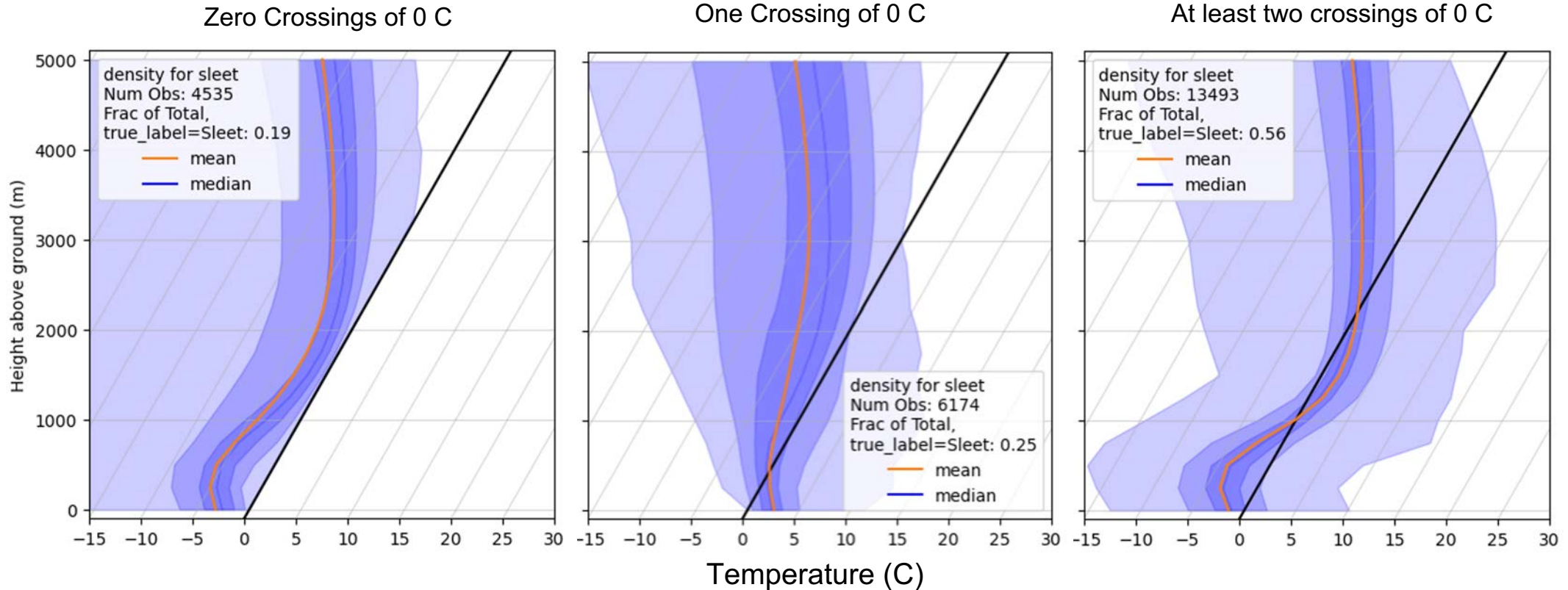
Evidential Model, Sleet



Root cause: Data Quality



- “ground truth” labels are from crowdsourced observations
- some quality control done, but not enough:



Post hoc XAI methods

Gradient * Input	Which features are most influential in predicting the model's output?
Shapley Additive Explanations (SHAP)	How much does each feature contribute to the model's predictions ?
Permutation Feature Importance	How does the performance of the model change when the information content of a feature is destroyed?

$$\mathbf{A}_{\text{Gradient} \odot \text{Input}}^c = \frac{\partial S_c(\mathbf{x})}{\partial \mathbf{x}} \odot \mathbf{x}.$$

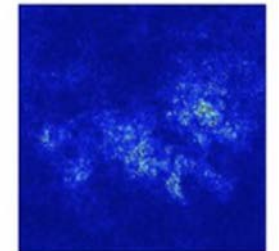
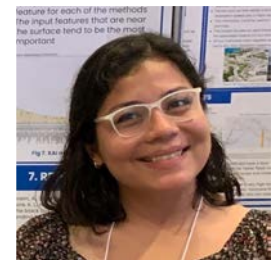
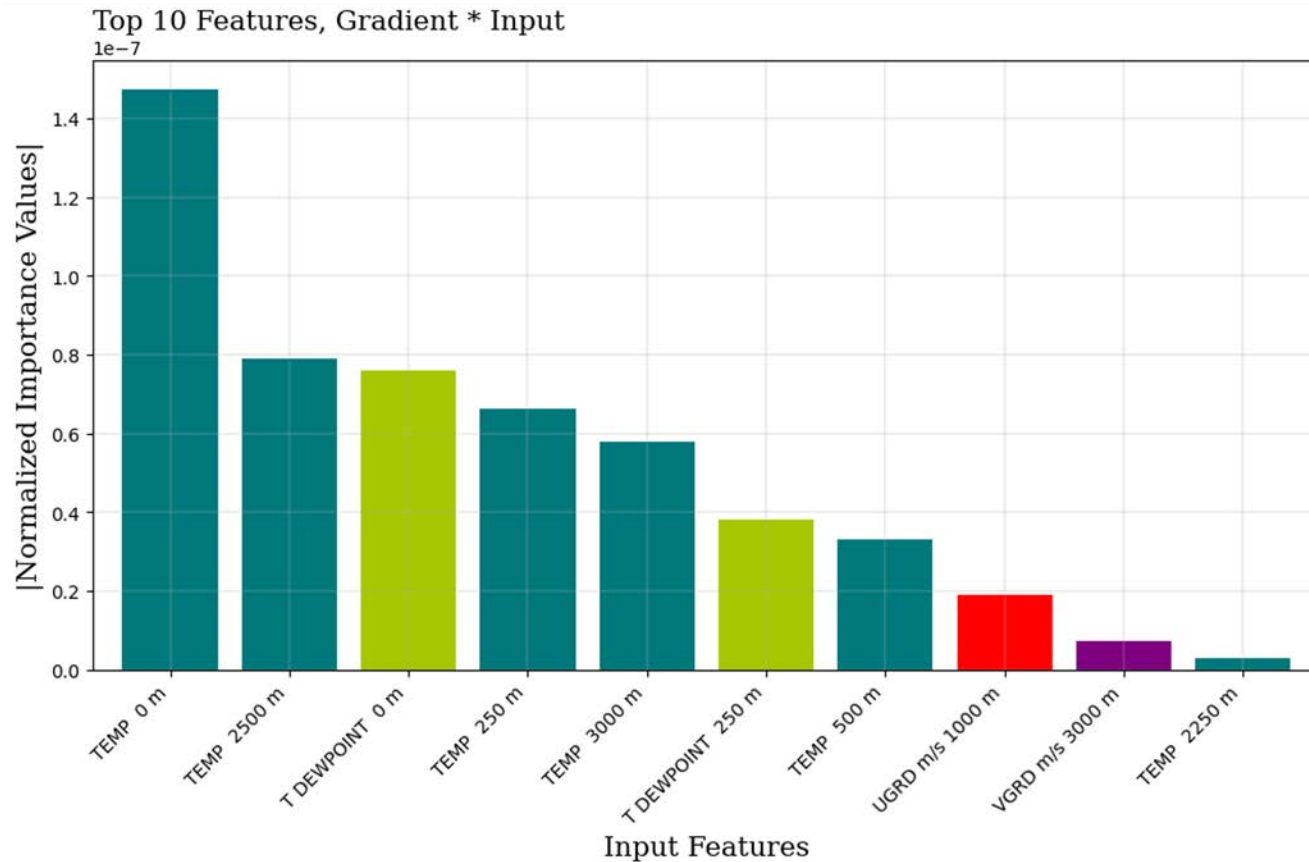


Fig. 3 Input * Gradient attribution method



Gradient * Input

Which **features are most influential** in predicting the model's output?

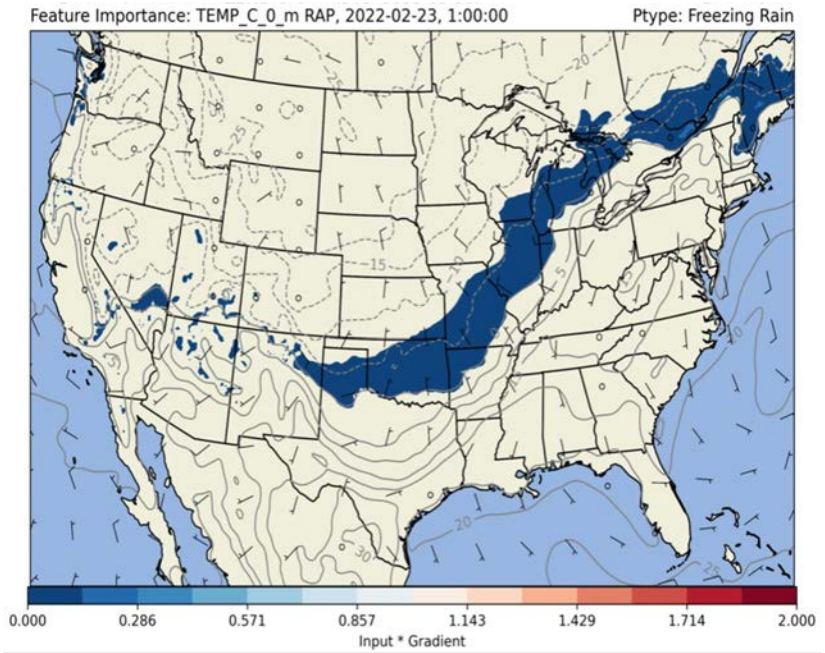
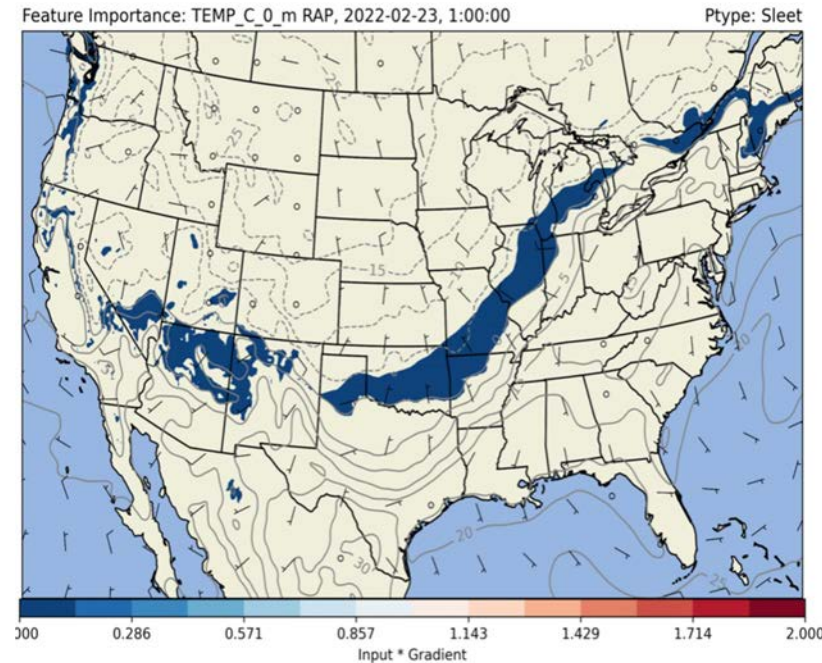
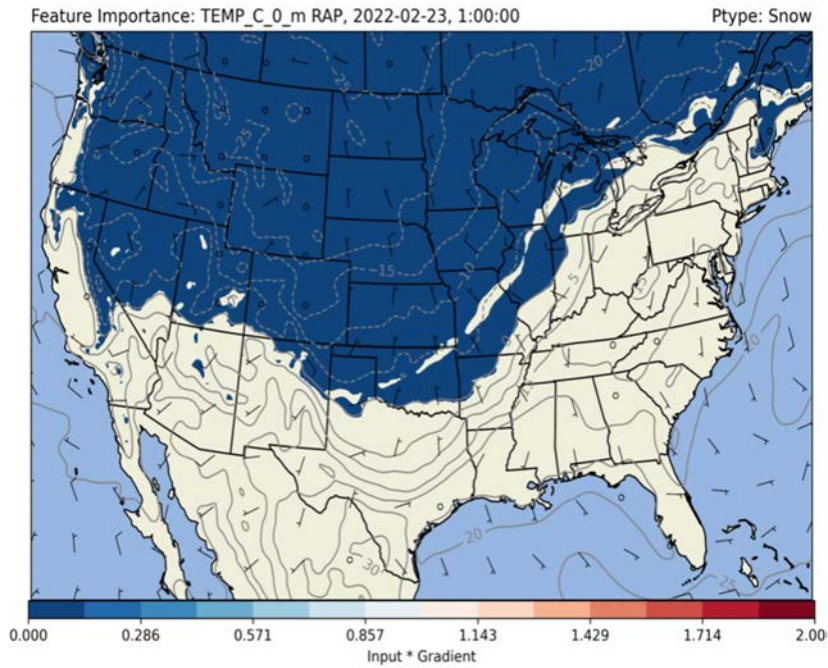


Gradient * Input works by multiplying the gradient of the model's output with the input features.

$$\mathbf{A}_{\text{Gradient} \odot \text{Input}}^c = \frac{\partial S_c(\mathbf{x})}{\partial \mathbf{x}} \odot \mathbf{x}.$$

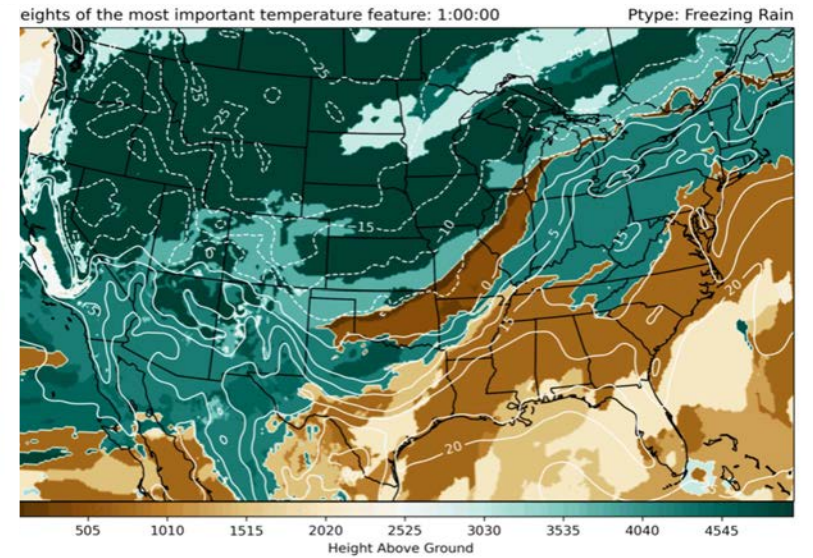
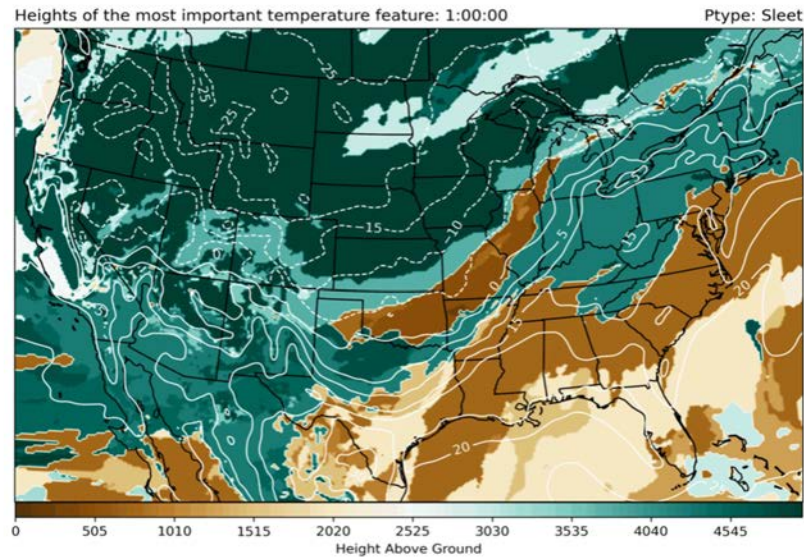
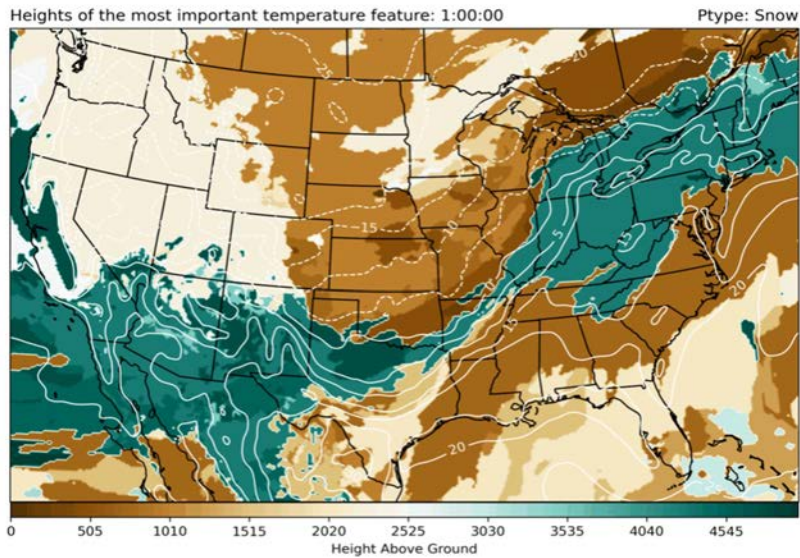
Gradient * Input: CONUS plots

Which **features** are most influential in predicting the model's output?



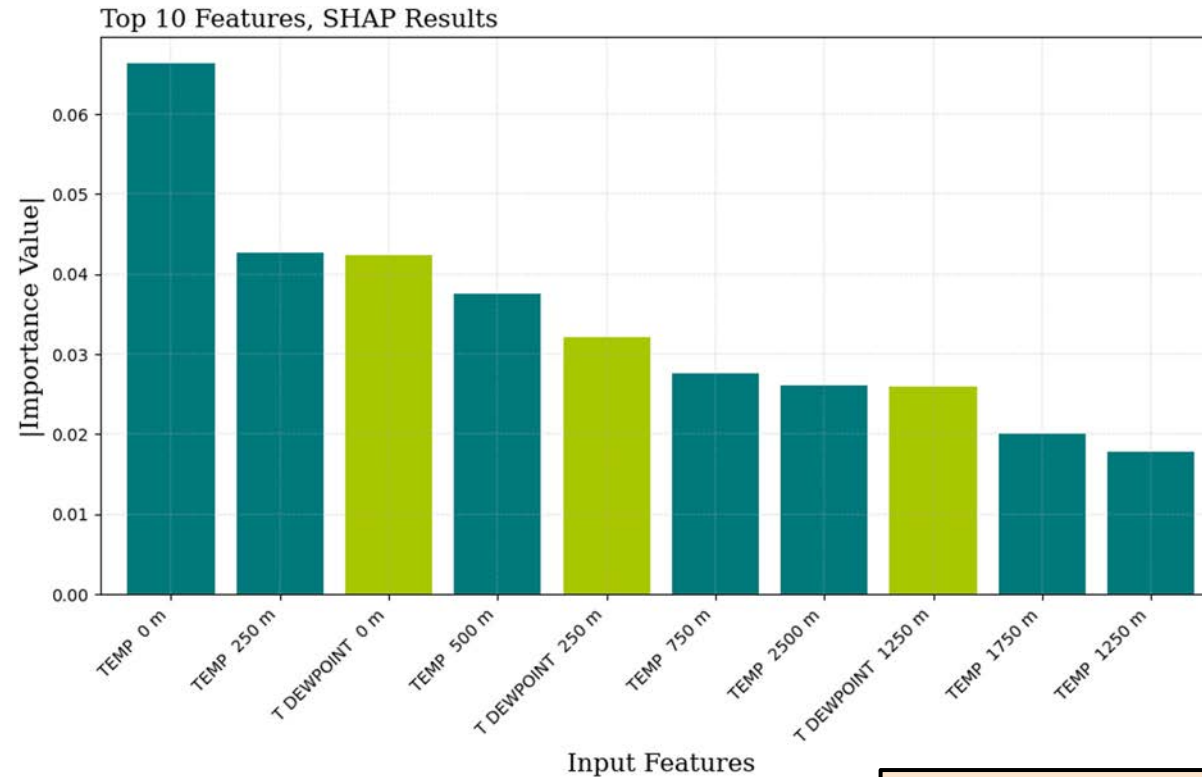
Gradient * Input: CONUS plots

Which **features are most influential** in predicting the model's output with respect to their height?



Shapley Additive Explanations (SHAP)

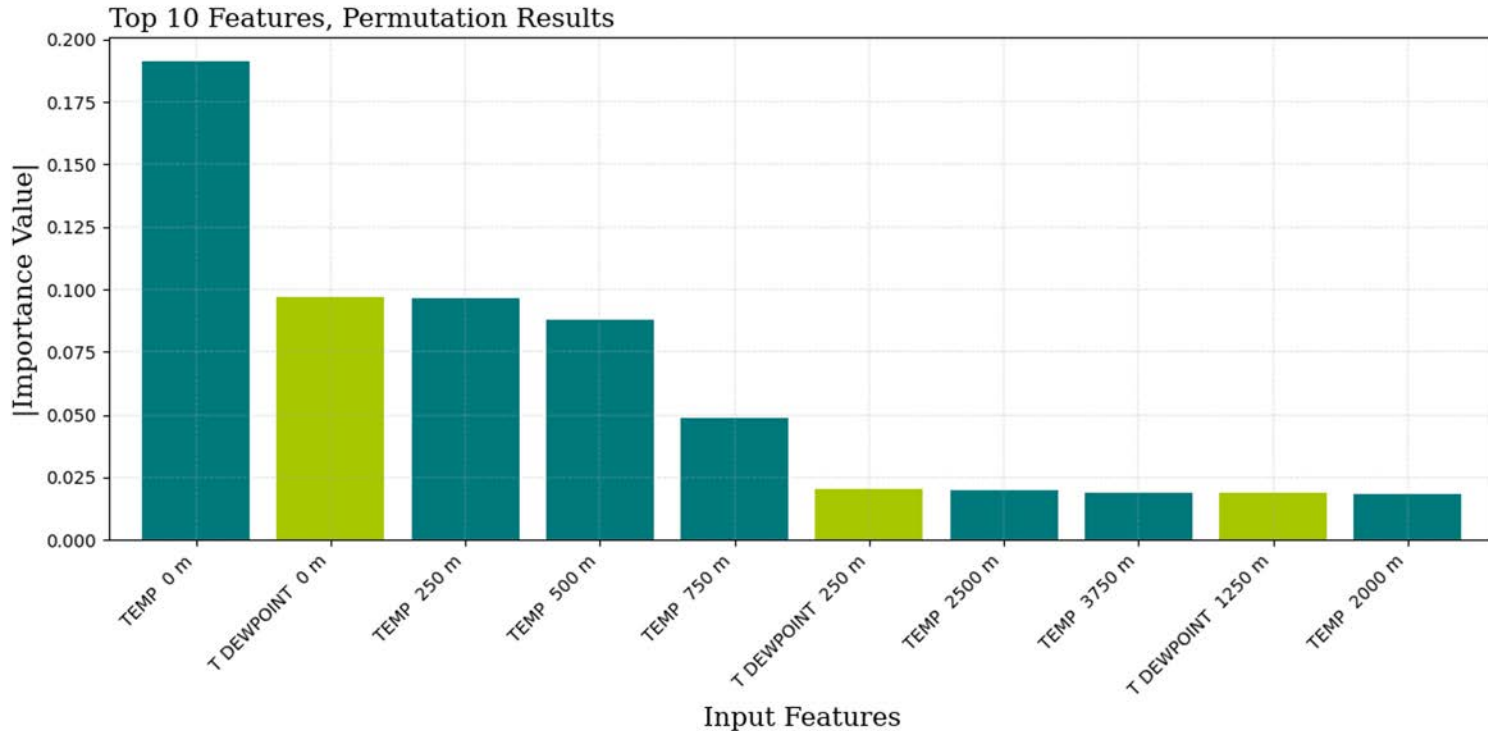
How much does **each feature contribute to the model's predictions?**



SHAP calculates the average contribution of each feature, representing how much each feature influences the model's prediction

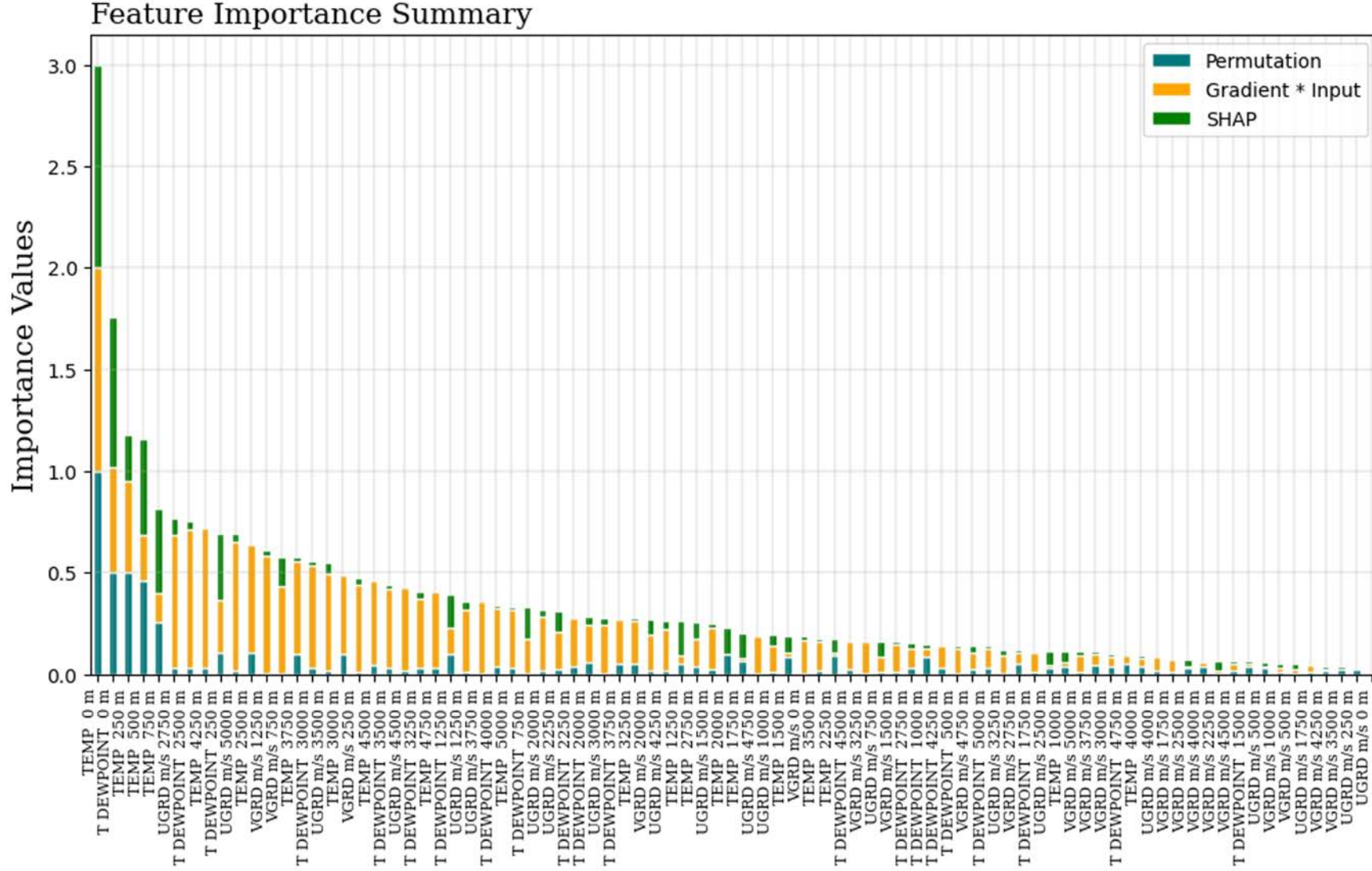
Permutation Feature Importance

What is the importance of each feature in predicting the model's output when the feature values are randomly shuffled?



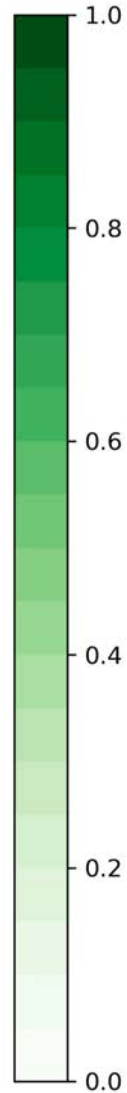
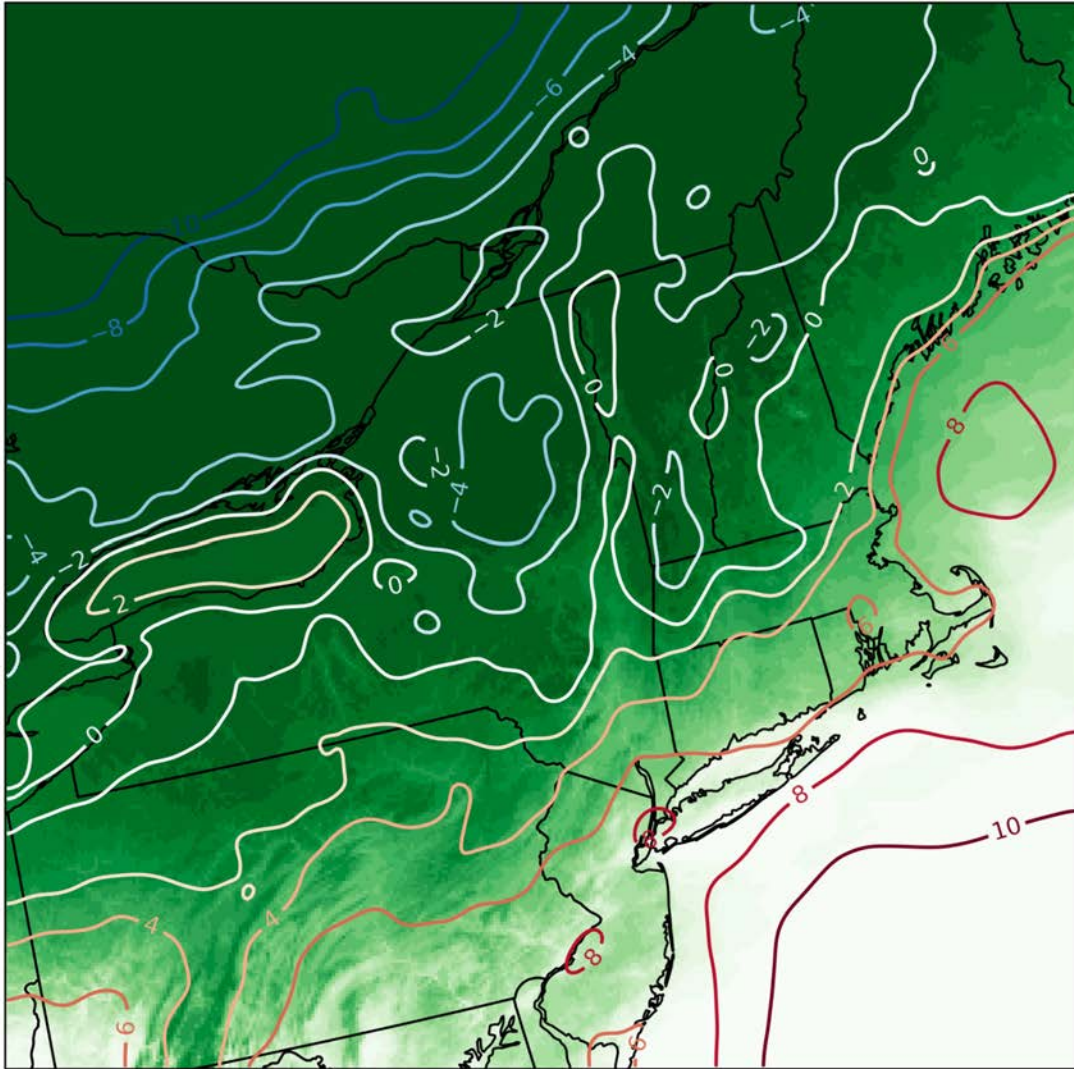
Permutation feature importance works by randomly shuffling the values of a single feature and measuring the resulting change in the model's performance. The feature with the largest change in performance is considered to be the most important feature.

XAI Results Summary



Transfer to Real-Time

HRRR ML Probability of Snow 2023-01-29 0000 UTC



- Planning to run in model in real-time on cloud this winter
- Working with risk communication team to perform interviews and/or experiments with stakeholders
- Have successfully run ML model on RAP, HRRR, and GFS in archival mode
- Partnered with Vaisala to test effect of ML p-type predictions on their road weather model

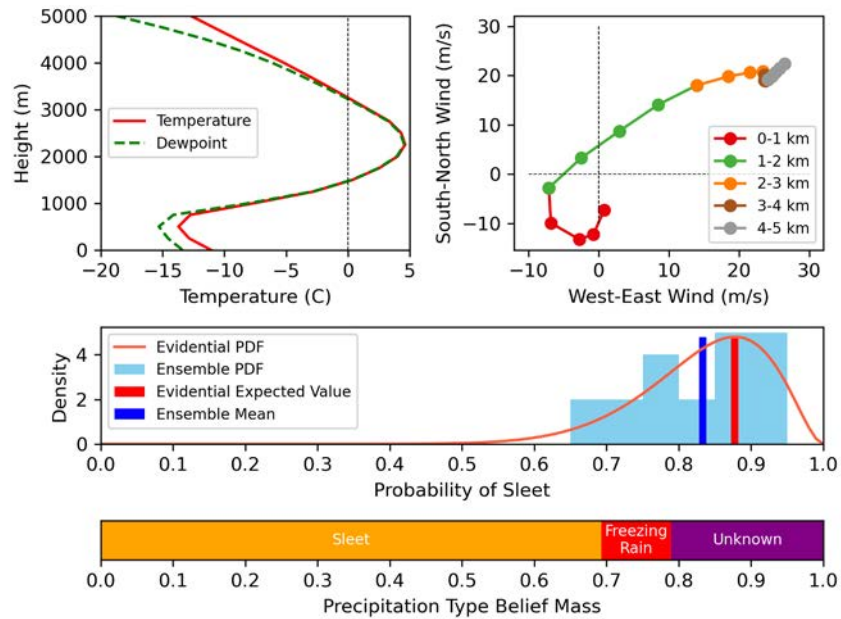
Limitations of Evidential Methods

- Requires calibration dataset to tune evidential regularizer coefficient
- Does not account for uncertainty in the inputs
- Uncertainty estimates will be underdispersive if the model is used outside its training context
 - e.g. train on observations/analysis but apply to forecast
 - transfer to different models
- No evidence prior may not be appropriate for rare events

MILES Group Python Packages

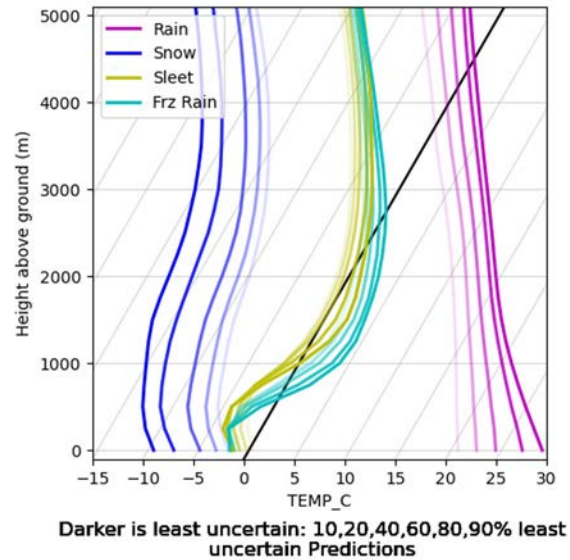
- **miles-guess** (github.com/ai2es/miles-guess):
 - Implementations of evidential neural networks, deep ensembles, and Monte Carlo dropout
- **echo-opt** (github.com/NCAR/echo-opt):
 - Distributed hyperparameter optimization on HPC systems
 - Supports GPU allocation, XAI visualization for hyperparameter settings
- **hagelslag** (github.com/djgagne/hagelslag):
 - Object segmentation, tracking, and data extraction for convection-allowing model output
 - verification scores and plots
- **bridgescaler** (github.com/NCAR/bridgescaler):
 - Reproducible saving/loading of sklearn preprocessing scalers and transforms
 - Custom scalers for groups of variables and image patches
- **m1inwrf** (github.com/NCAR/m1inwrf):
 - Neural network and random forest implementations in Fortran
- **mlmicrophysics** (github.com/NCAR/mlmicrophysics):
 - Bin microphysics emulator for CAM/CESM

Summary

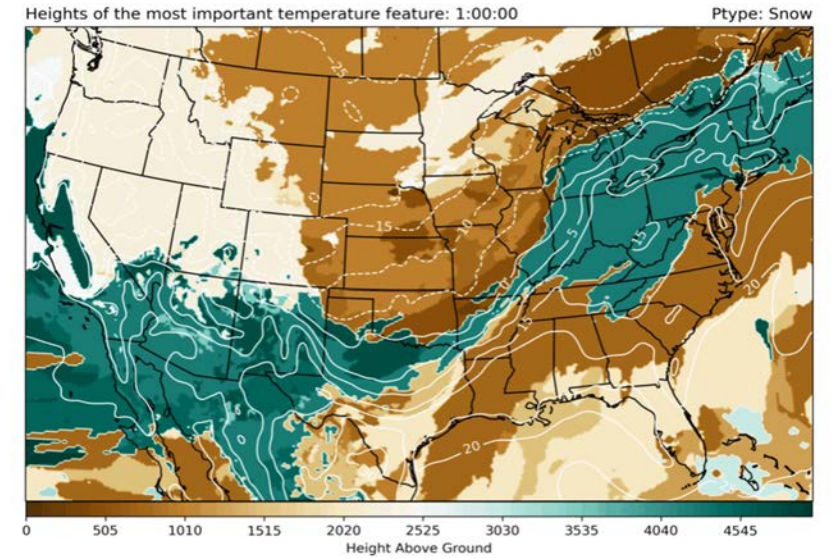


Evidential deep learning provides more comprehensive predictive uncertainty quantification.

Median Soundings by Evidential Uncertainty



Can composite soundings by uncertainty and get meaningful features



XAI diagnostics help connect predictions with atmospheric features.